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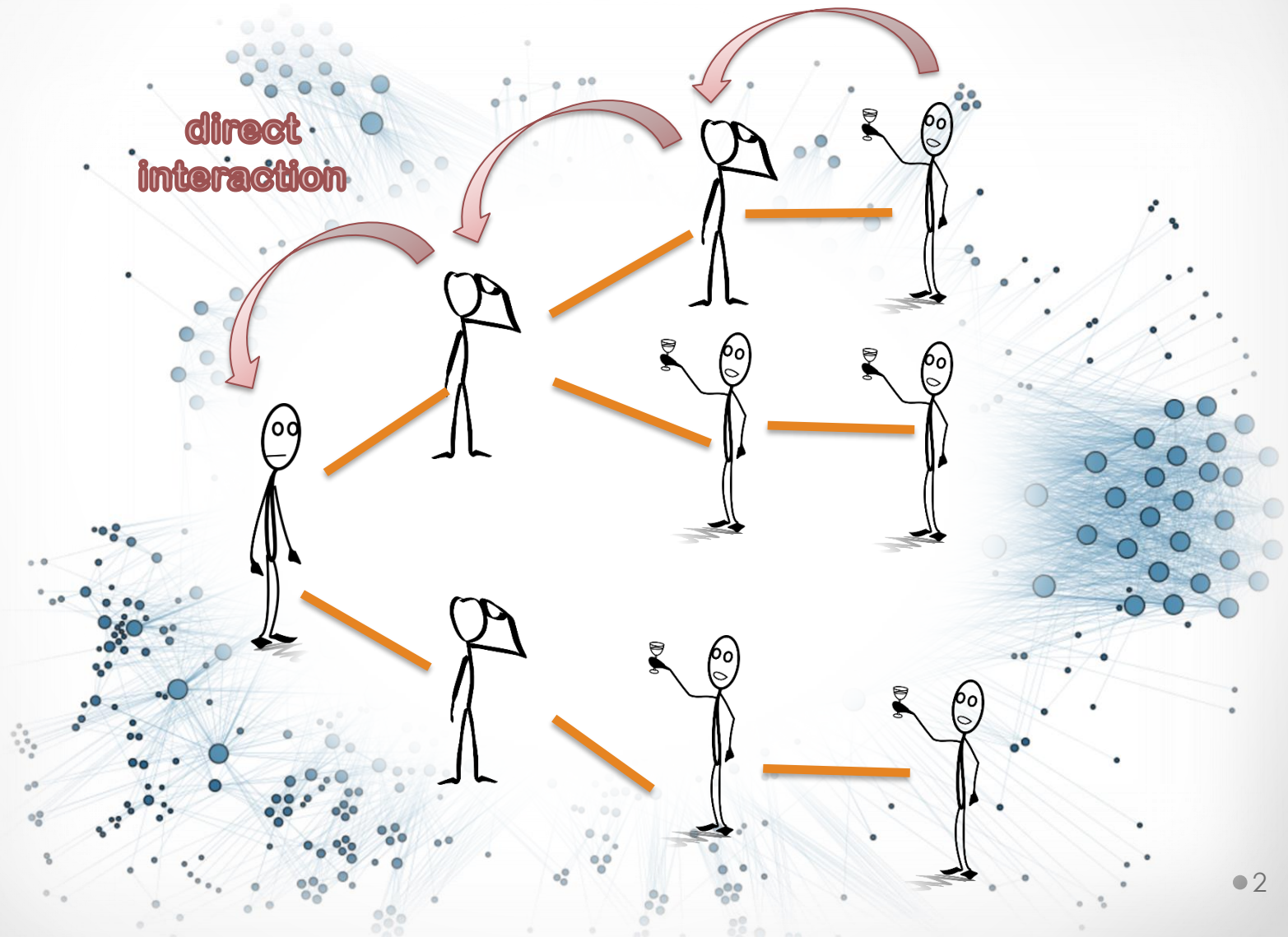
Long-Range Influences in (Social) Networks

Ernesto Estrada

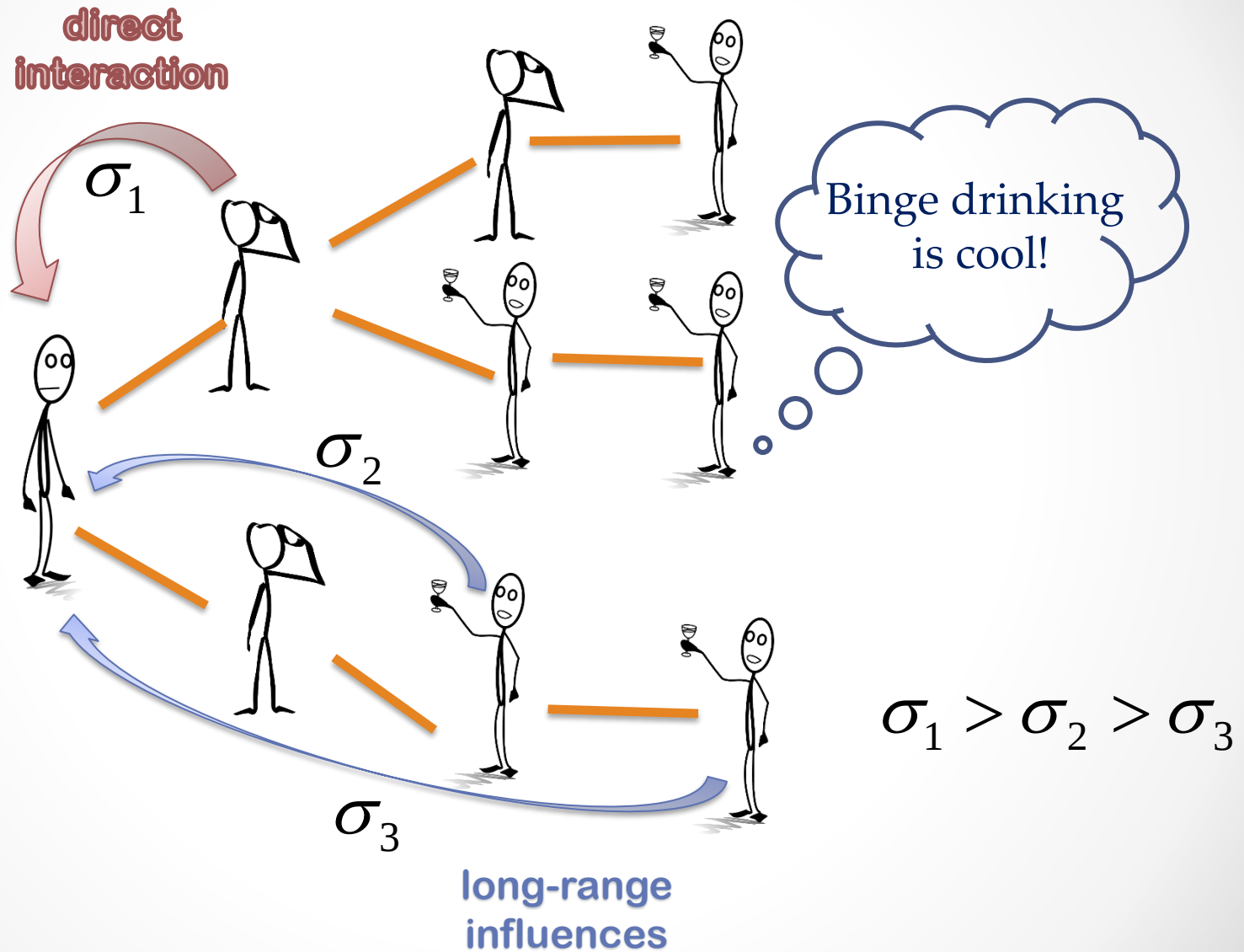
ernesto.estrada@strath.ac.uk
www.estradalab.org
@eestradalab

The Network Paradigm

“In a network dynamical processes, at a given time step, “information” is transmitted to nearest-neighbours ONLY”

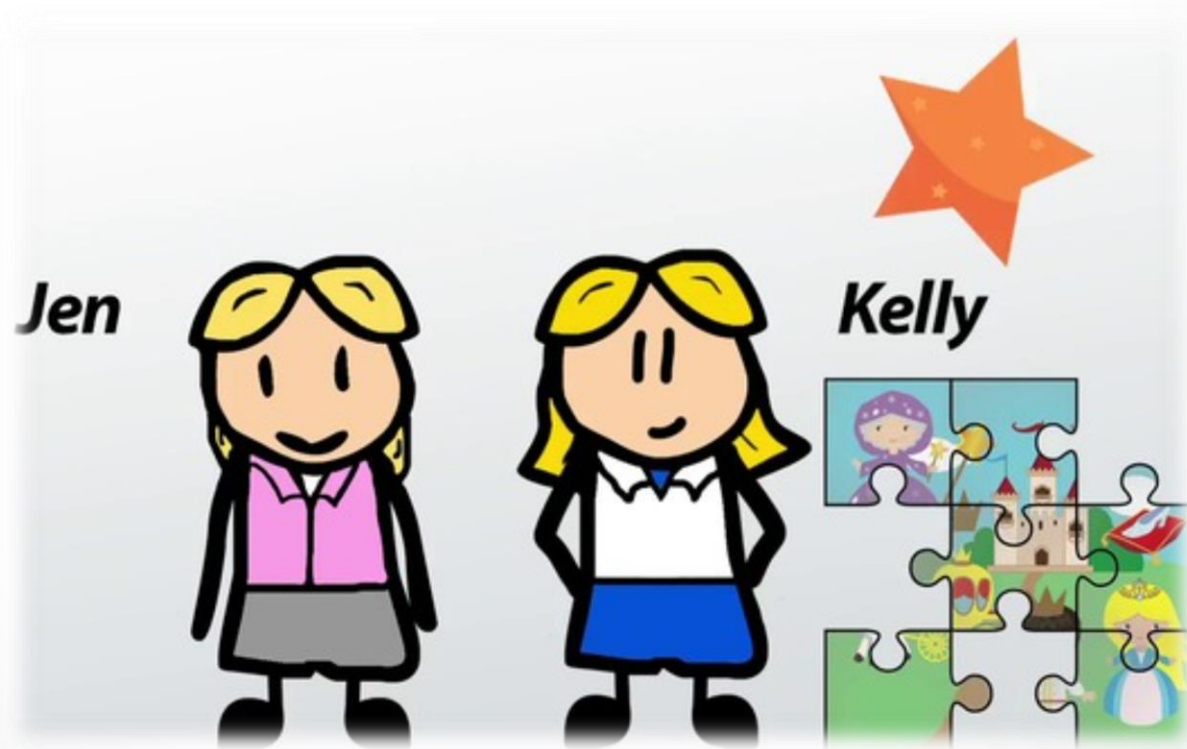


What IF...?



Indirect peer pressure

“**direct peer pressure** may involve verbal and nonverbal attempts at persuasion, **indirect peer pressure** encompasses more subtle forms of influence, such as modeling and vicarious reinforcement”.



Examples of indirect social pressure

- *“The indirect social pressure: most families install this type of windows as a symbol of their social condition; Installing thermal insulated windows turned into a “fashion”.”*

Iancu, Bogdan, Martor 16 (2011) 19-33.

- *Creating a feeling of “if it is OK for them, must be OK for me too”*

- *Use of (social) media:*





Mathematical framework



The mathematical framework

$$G = (V, E)$$

nodes or vertices

$$V = \{v_1, \dots, v_n\}$$

edges or links

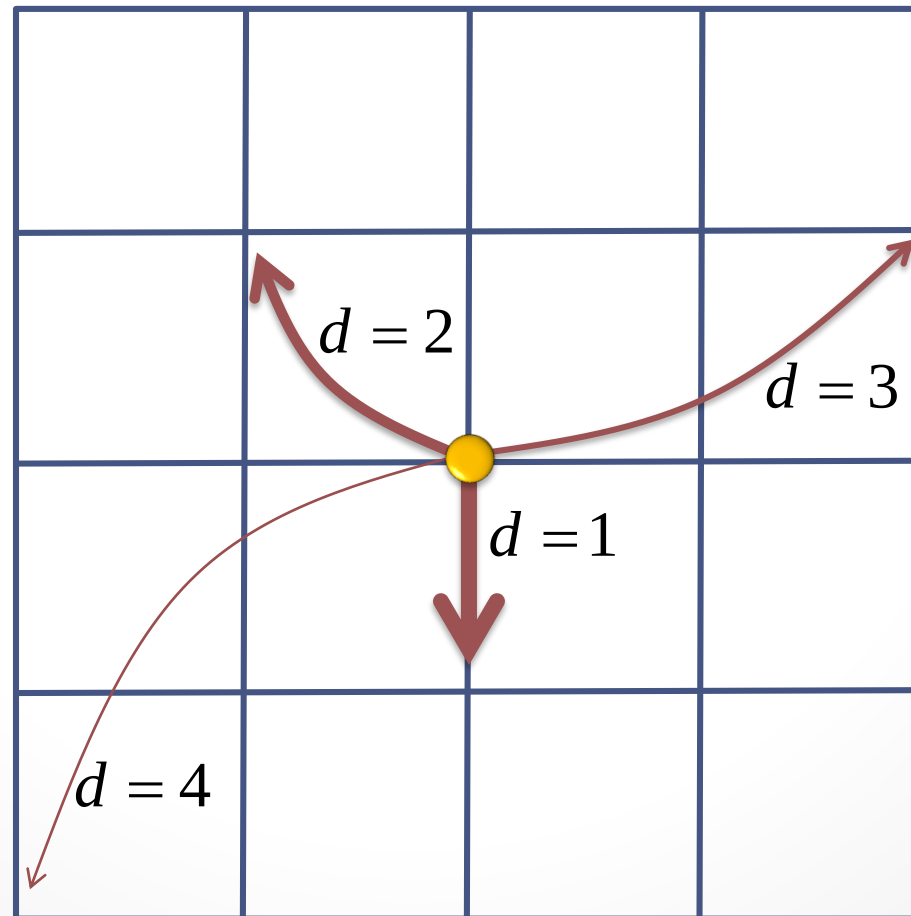
$$E \subseteq V \times V$$

- We consider here simple, finite or locally-finite infinite graphs.

Estrada & Knight: *A First Course on Network Theory*, Oxford Univ. Press, 2015

The mathematical framework

Let us consider that the “information” at a given node can hop not only to its nearest neighbours but to any other node of the network with a probability that decays with the shortest path distance from its current position.



The mathematical framework

Let d be the shortest path distance on $G = (V, E)$.

Let $\delta_d(v)$ be the d -path degree of the vertex v , i.e.,

$$\delta_d(v) := \# \{w \in V : d(v, w) = d\}.$$

Since G is locally finite, $\delta_d(v)$ is finite for every $v \in V$.

Estrada, *Lin. Algebra Appl.*, **436**, 3373, 2012.

Estrada et al., *Lin. Algebra Appl.*, **523**, 307-334, 2017.

The mathematical framework

Let $C(V)$ be the set of all complex-valued functions on V .

Let $\ell^2(V)$ be the Hilbert space of square-summable functions on V with inner product

$$\langle f, g \rangle = \sum_{v \in V} f(v) \bar{g}(v), \quad f, g \in \ell^2(V)$$

Definition: *The d -path Laplacian operator on graphs is the following mapping of $C(V)$ into itself:*

$$(L_d f)(v) := \sum_{w \in V: d(v, w) = d} (f(v) - f(w)), \quad f \in C(V).$$

Estrada, *Lin. Algebra Appl.*, **436**, 3373, 2012.

Estrada et al., *Lin. Algebra Appl.*, **523**, 307-334, 2017.

The mathematical framework

Let e_v , $v \in V$, be a standard orthonormal basis in $\ell^2(V)$, where

$$e_v(w) = \begin{cases} 1 & \text{if } w = v \\ 0 & \text{otherwise.} \end{cases}$$

Then,

$$(L_d e_v)(w) = \begin{cases} \delta_d(v) & \text{if } w = v \\ -1 & \text{if } d(v, w) = d \\ 0 & \text{otherwise.} \end{cases}$$

Estrada, *Lin. Algebra Appl.*, **436**, 3373, 2012.

Estrada et al., *Lin. Algebra Appl.*, **523**, 307-334, 2017.

Transformed Laplacian operators

Let:

$$\tilde{L} := \sum_{d=1}^{\infty} c_d L_d, \quad c_d \in \mathbb{R}^+$$

If all L_d are bounded and

$$\sum_{d=1}^{\infty} \|c_d\| \|L_d\| < \infty,$$

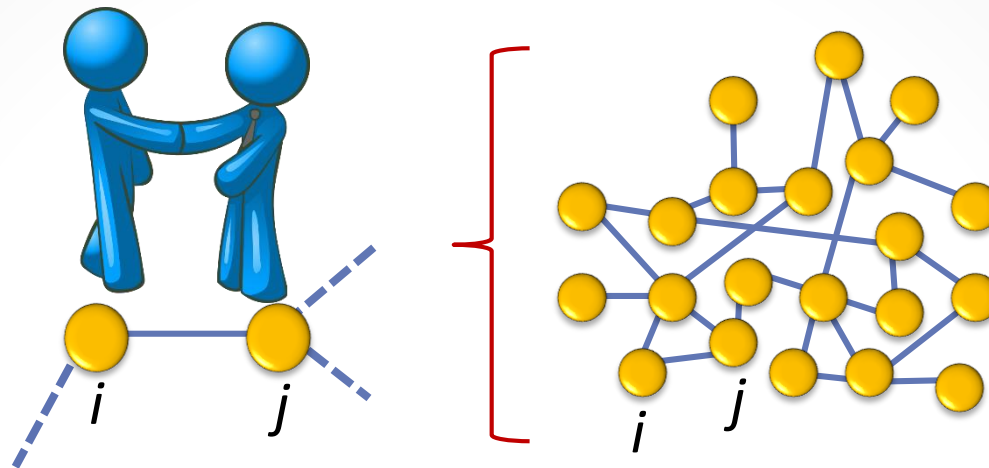
Then, $\tilde{L}$ is:

- *a bounded operator on $\ell^2(V)$,*
- *self-adjoint and,*
- *non-negative.*

Consensus



Consensus on networks



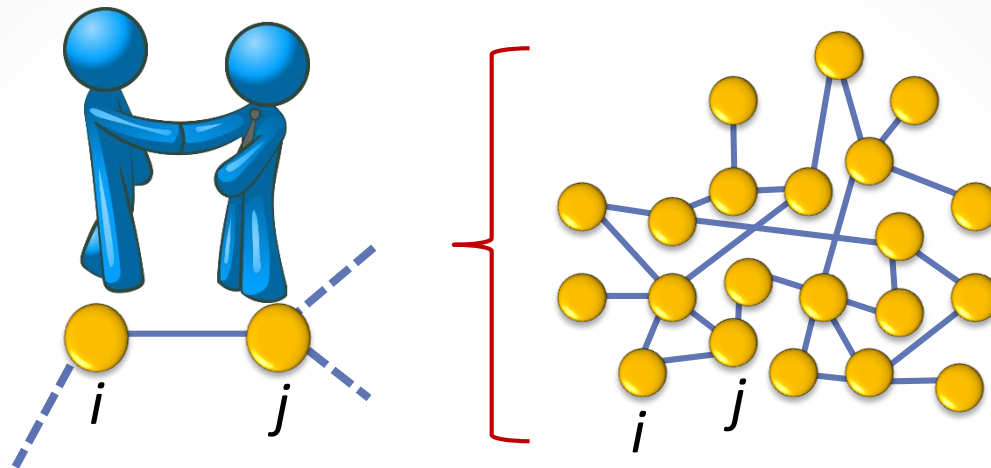
state of j at time t

state of i at time t

$$\frac{du_i}{dt} = \dot{u}_i(t) = \sum_{(i,j) \in E} [u_j(t) - u_i(t)], \quad i = 1, \dots, n$$

$$u_i(0) = z_i, \quad z_i \in \mathbb{R}$$

Consensus on networks



In matrix-vector form:

$$\vec{\dot{u}}(t) = -L(G)\vec{u}(t), \quad \vec{u}(0) = \vec{u}_0$$

where

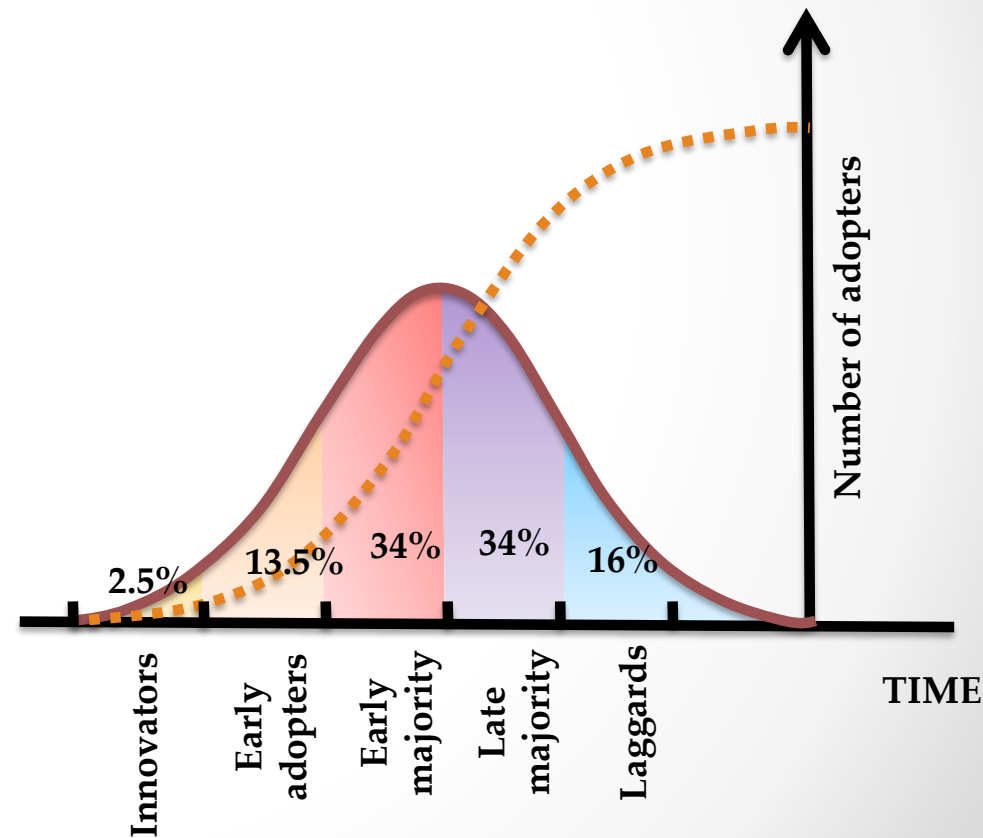
$$L_{uv} = \begin{cases} -1 & \text{if } (uv) \in E, \\ k_u & \text{if } u = v, \\ 0 & \text{otherwise.} \end{cases}$$

Consensus on networks

SOCIAL CONSENSUS

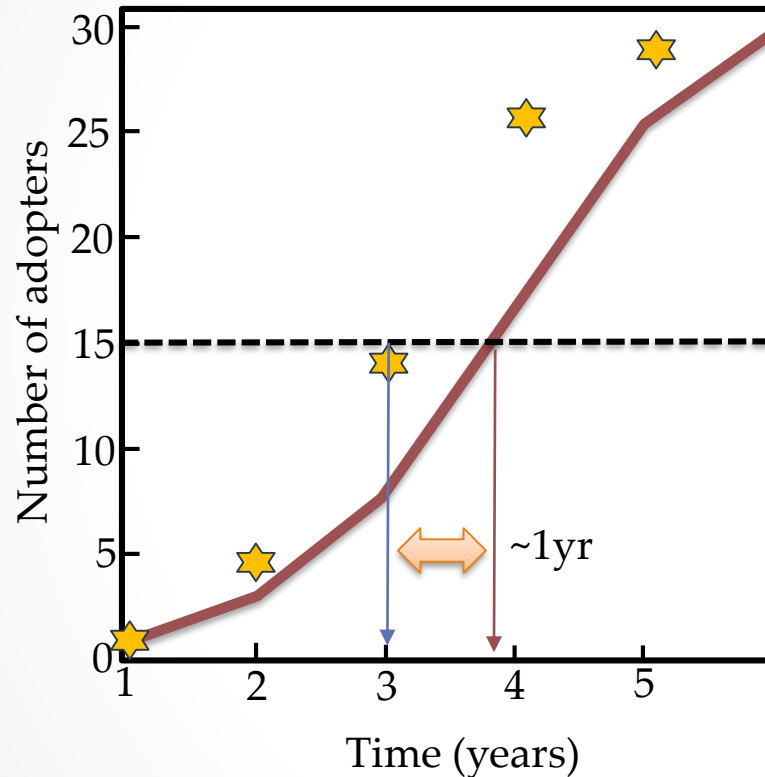


DIFFUSION OF INNOVATIONS

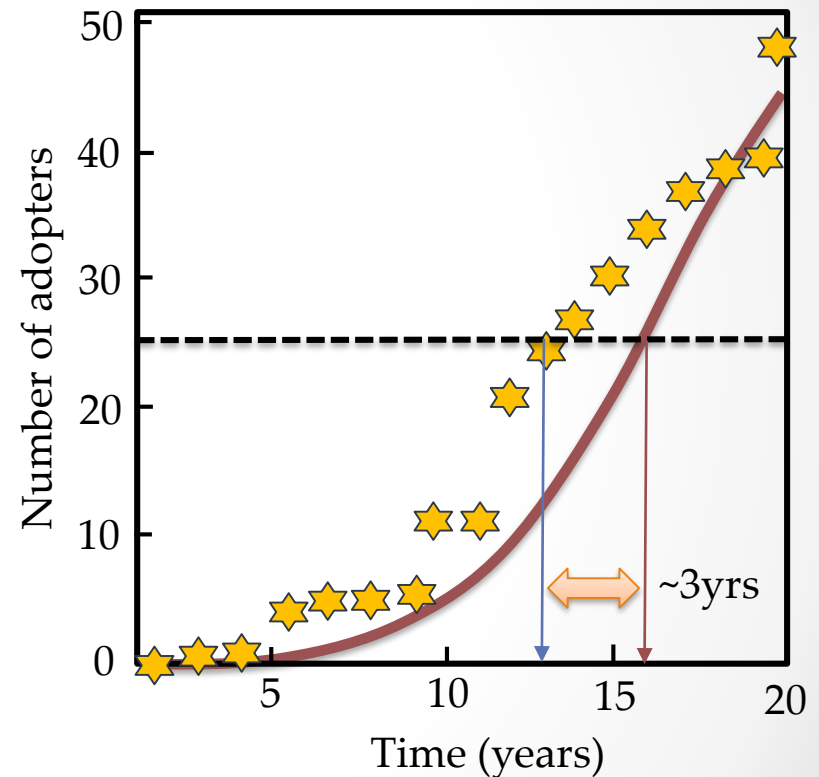


Diffusion of innovations

Diffusion of a mathematical method among high schools



Diffusion of a biotech product among Brazilian farmers



- ★ Observation
- Normal diffusion

Generalised consensus on networks

We can now generalise the diffusion dynamics equation to account for such long-range hops:

$$\vec{u}(t) = -\tilde{L}\vec{u}(t) \quad u(0) = u_0$$

$$\tilde{L}_{t=\{s,\lambda\}} = \sum_{d=1}^{\Delta} c_d L_d$$

Mellin transform

$$c_d = d^{-s},$$

$$s \in \mathbb{R}^+$$

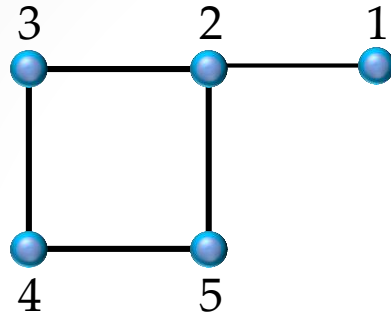
Laplace transform

$$c_d = \exp(-\lambda \cdot d),$$

$$\lambda \in \mathbb{R}^+$$

Generalised consensus on networks

Example:



$$\tilde{L}_s = \sum_{d=1}^{\Delta} c_d L_d$$

Mellin transformed Laplacian

$$\tilde{L}_s = \begin{bmatrix} 1 + 2 \cdot 2^{-s} + 3^{-s} & -1 & -2^{-s} & -3^{-s} & -2^{-s} \\ -1 & 3 + 2^{-s} & -1 & -2^{-s} & -1 \\ -2^{-s} & -1 & 2 + 2 \cdot 2^{-s} & -1 & -2^{-s} \\ -3^{-s} & -2^{-s} & -1 & 2 + 2^{-s} + 3^{-s} & -1 \\ -2^{-s} & -1 & -2^{-s} & -1 & 2 + 2 \cdot 2^{-s} \end{bmatrix}$$

Generalised consensus on networks

Example:

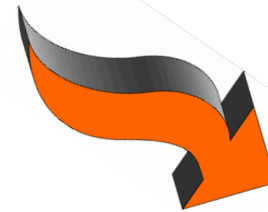
$$\tilde{L}_s = \begin{bmatrix} 1 + 2 \cdot 2^{-s} + 3^{-s} & -1 & -2^{-s} & -3^{-s} & -2^{-s} \\ -1 & 3 + 2^{-s} & -1 & -2^{-s} & -1 \\ -2^{-s} & -1 & 2 + 2 \cdot 2^{-s} & -1 & -2^{-s} \\ -3^{-s} & -2^{-s} & -1 & 2 + 2^{-s} + 3^{-s} & -1 \\ -2^{-s} & -1 & -2^{-s} & -1 & 2 + 2 \cdot 2^{-s} \end{bmatrix}$$

$s \rightarrow \infty$



$$L(G) = \begin{bmatrix} 1 & -1 & 0 & 0 & 0 \\ -1 & 3 & -1 & 0 & -1 \\ 0 & -1 & 2 & -1 & 0 \\ 0 & 0 & -1 & 2 & -1 \\ 0 & -1 & 0 & -1 & 2 \end{bmatrix}$$

$s \rightarrow 0$



$$L(K_n) = \begin{bmatrix} 4 & -1 & -1 & -1 & -1 \\ -1 & 4 & -1 & -1 & -1 \\ -1 & -1 & 4 & -1 & -1 \\ -1 & -1 & -1 & 4 & -1 \\ -1 & -1 & -1 & -1 & 4 \end{bmatrix}$$

How fast
can it go?



Recall that...

normal diffusion

$$MSD \sim t$$

$$(u(t))_x = \frac{1}{2\sqrt{\pi\alpha t}} \exp\left(-\frac{x^2}{4\alpha t}\right)$$

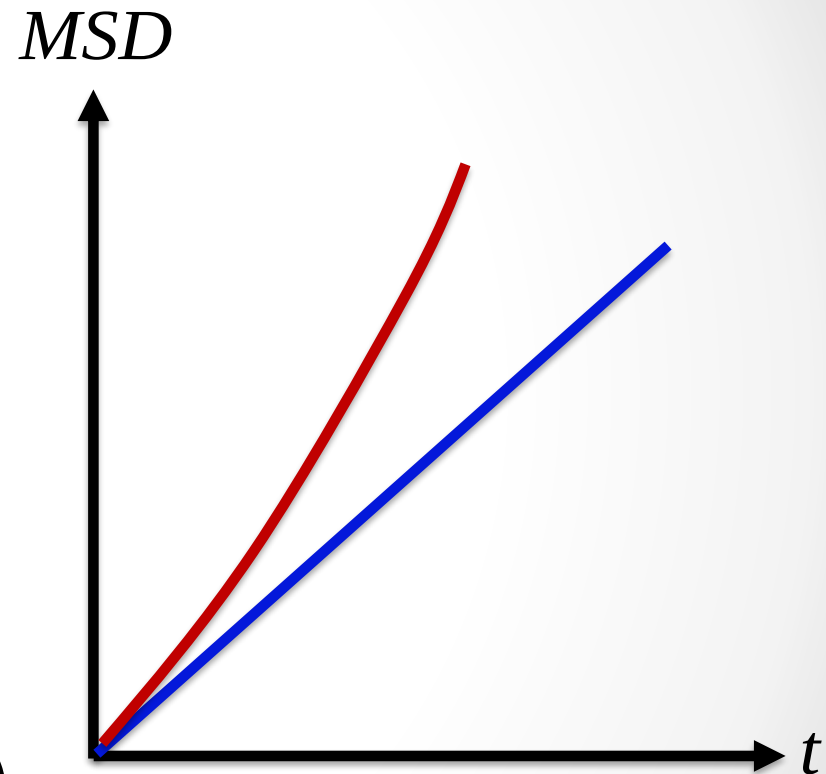
$$FWHM(t) \sim t^{1/2}$$

superdiffusion

$$MSD \sim t^\alpha, \alpha > 1$$

$$(u(t))_x = t^{-1/\alpha} f\left(t^{-1/\alpha} x; \alpha, 0, \gamma, 0\right)$$

$$FWHM(t) \sim t^\alpha, \alpha > 1/2$$



GDE in one-dimension

Theorem: Let P_∞ be the infinite path graph, let $\lambda > 0$ and $\tilde{L}_\lambda$ be the Laplace-transformed d -path Laplacian with parameter λ . Moreover, let $u(t)$ be the solution of the generalised diffusion equation with $L = L_d$ or $L = \tilde{L}_\lambda$. Then, as $t \rightarrow \infty$

$$(u(t))_x = t^{-1/2} \frac{1}{2\sqrt{\pi a}} \exp\left(-\frac{x^2}{4at}\right) + o(t^{-1/2})$$

uniformly in $x \in \mathbb{Z}$ where

$$a = d^2$$

$$\text{for } L = L_d$$

$$a = \frac{e^\lambda (e^\lambda + 1)}{(e^\lambda - 1)^3} = \frac{\coth\left(\frac{\lambda}{2}\right)}{2(\cosh \lambda - 1)}$$

$$\text{for } L = \tilde{L}_\lambda.$$

Resume

Laplace-transform

$$(u(t))_x = \frac{1}{2\sqrt{\pi\alpha t}} \exp\left(-\frac{x^2}{4\alpha t}\right)$$

$$FWHM(t) = 2\sqrt{\ln(2)\alpha t}$$

$$FWHM(t) \sim t^{1/2}$$

NOTHING NEW

NORMAL DIFFUSION

GDE in one-dimension

Theorem: Let P_∞ be the infinite path graph, let $s > 1$ and $\tilde{L}_s$ be the Mellin-transformed k -path Laplacian with parameter s . Moreover, let $u(t)$ be the solution of the generalised diffusion equation with $L = \tilde{L}_s$. Then

$$(u(t))_x = t^{-1/\alpha} f(t^{-1/\alpha} x; \alpha, 0, \gamma, 0) + o(t^{-1/\alpha}) \quad \text{as } t \rightarrow \infty$$

uniformly in $x \in \mathbb{Z}$ where

$$\alpha = s - 1, \quad \gamma = \left(-\frac{\pi}{\Gamma(s) \cos\left(\frac{\pi s}{2}\right)} \right)^{\frac{1}{s-1}} \quad \text{if } 1 < s < 3$$

$$\alpha = 2, \quad \gamma = \sqrt{\zeta(s-2)} \quad \text{if } s > 3.$$

Resume

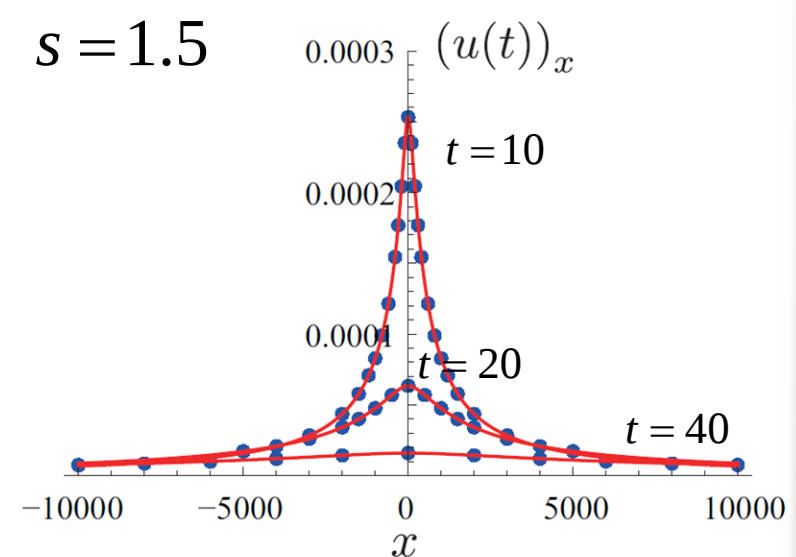
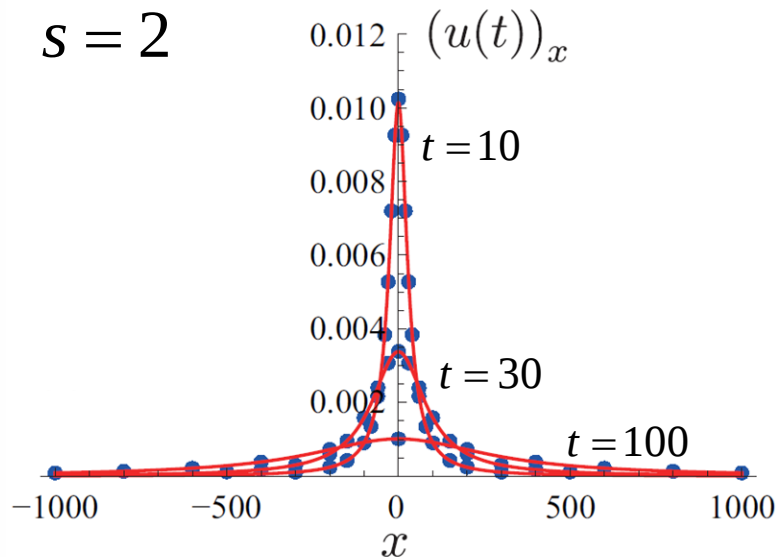
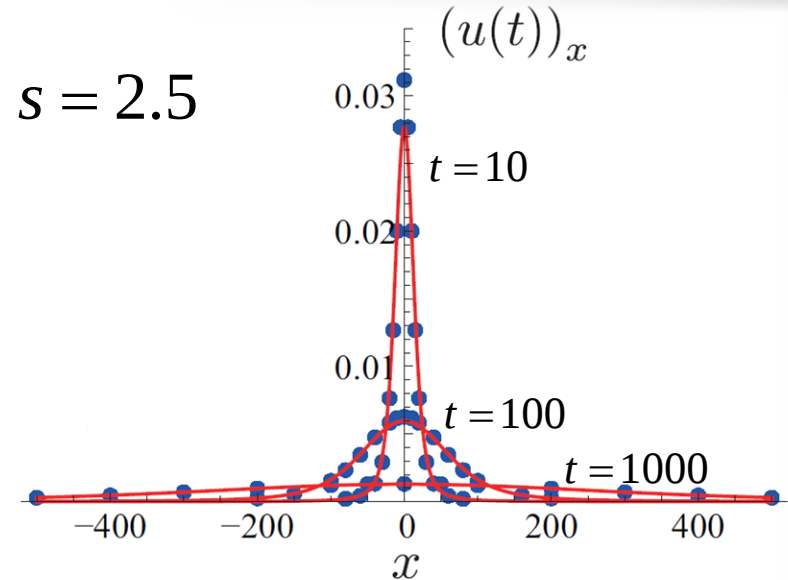
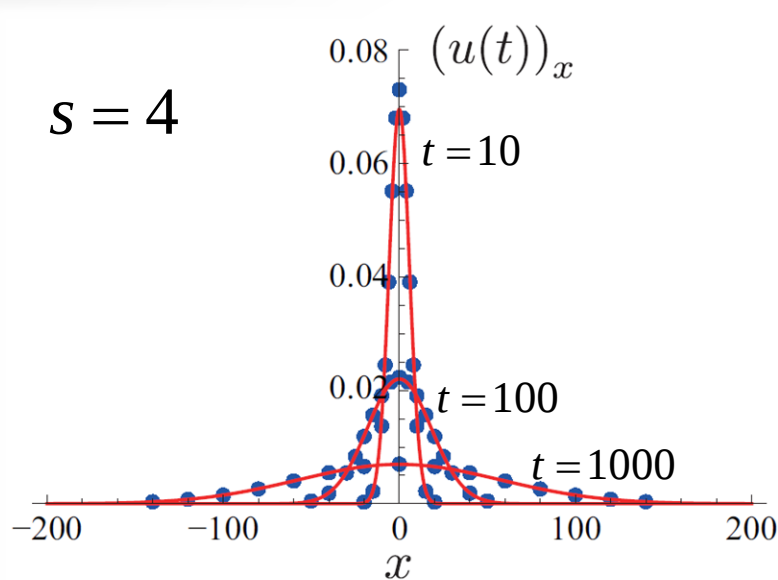
Mellin-transform $1 < s < 3$

$$(u(t))_x = t^{-1/\alpha} f(t^{-1/\alpha} x; \alpha, 0, \gamma, 0) + o(t^{-1/\alpha})$$

$$FWHM(t) \sim 2\xi_0 t^{1/(s-1)}$$

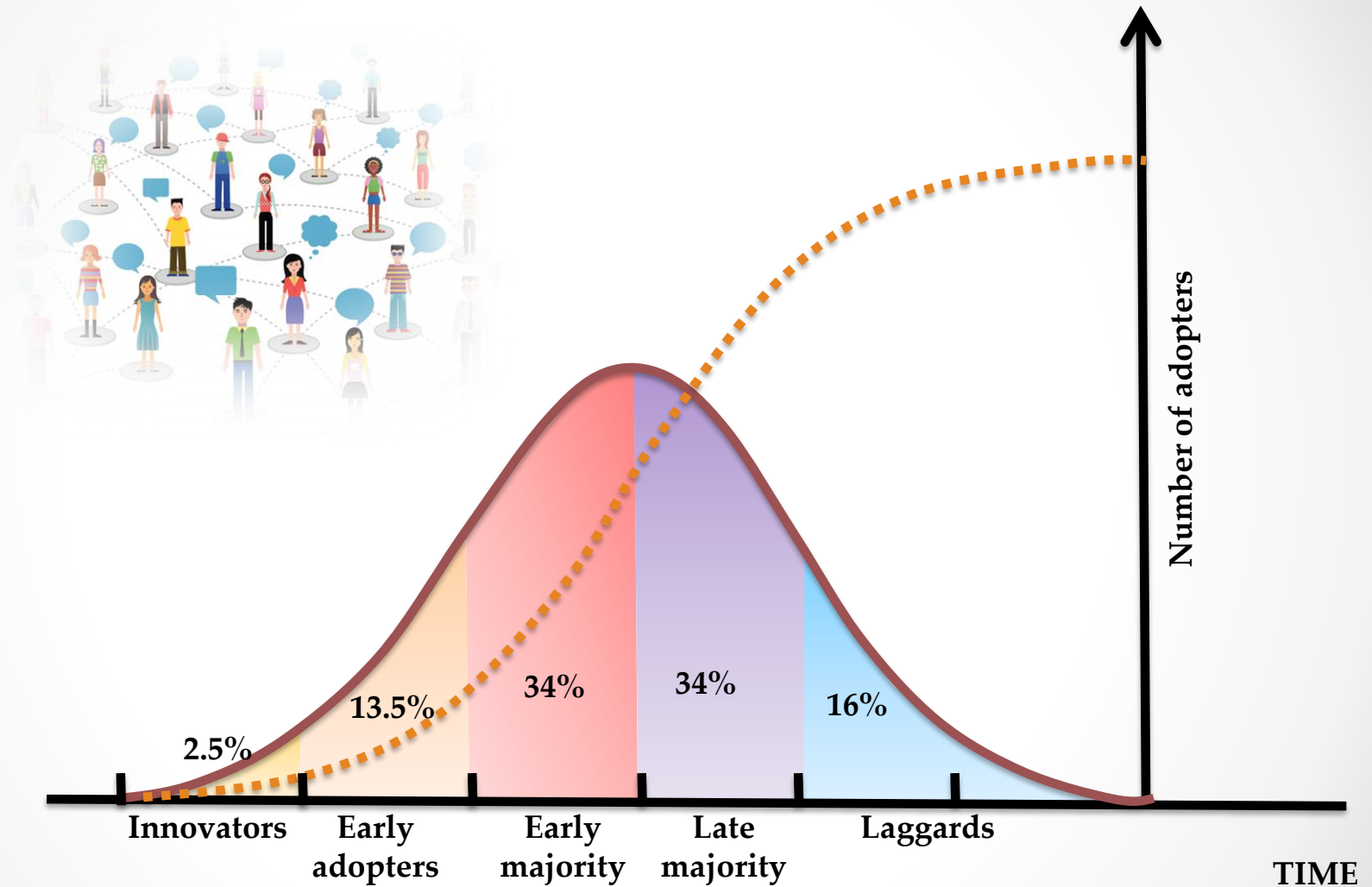
SUPERDIFFUSION (!)

GDE in one-dimension



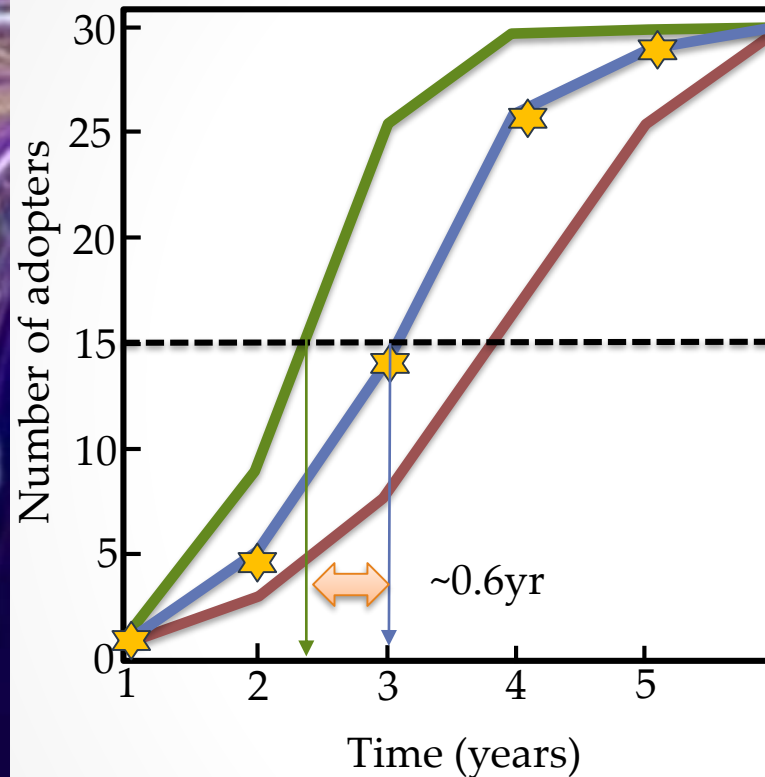
Estrada et al., *Lin. Algebra Appl.*, **523**, 307-334, 2017.

Back to diffusion of innovations



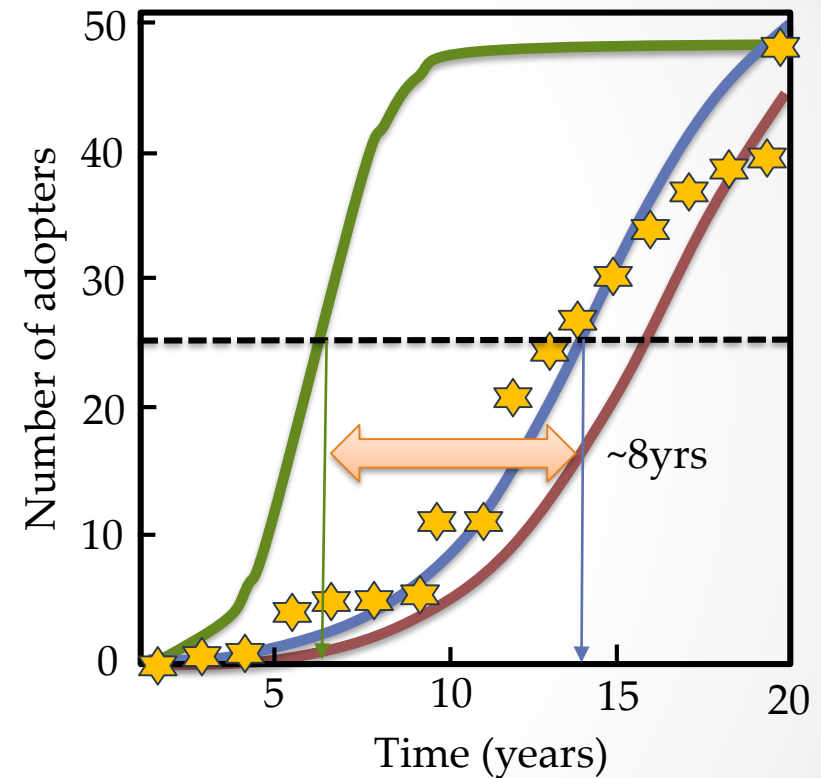
GDE and diffusion of innovations

Diffusion of a mathematical method among high schools



★ Observation
— No indirect peers pressure

Diffusion of a biotech product among Brazilian farmers

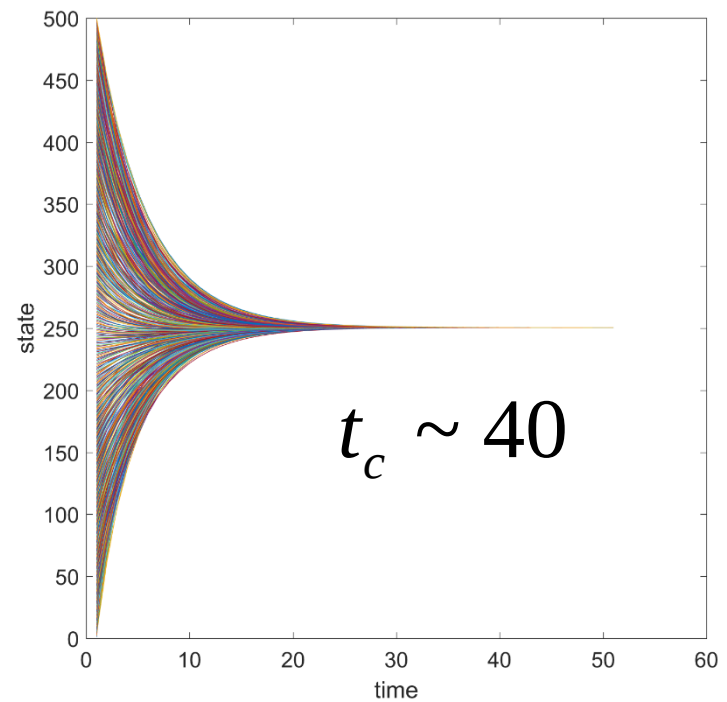
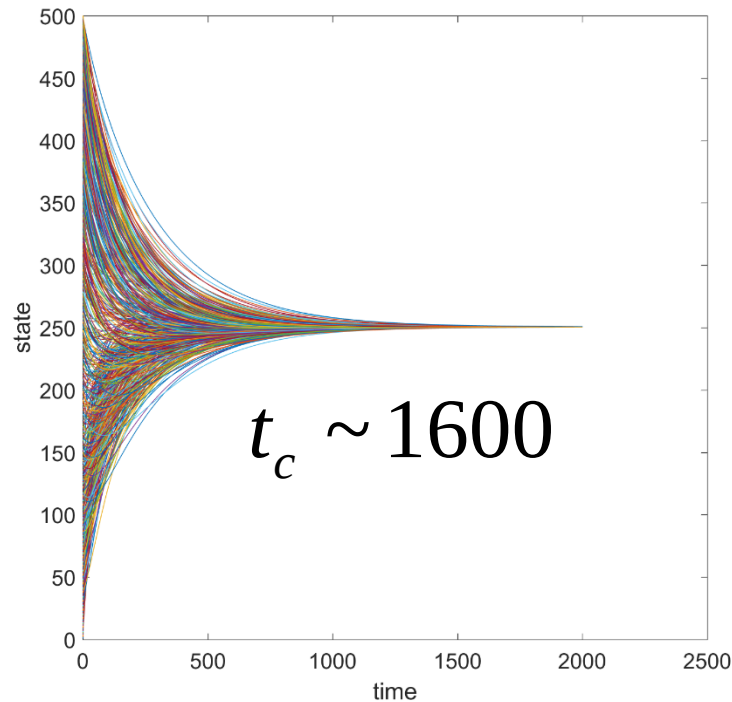


— Moderate indirect peers pressure
— High indirect peers pressure

How much acceleration of consensus?

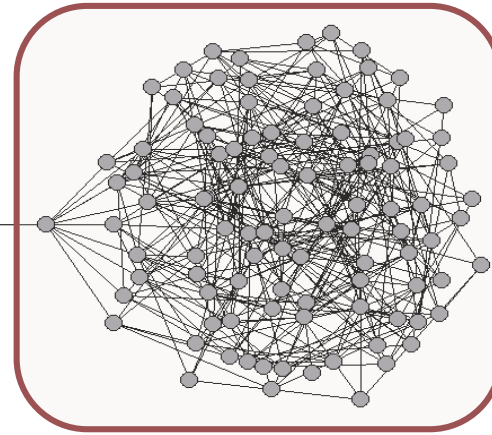
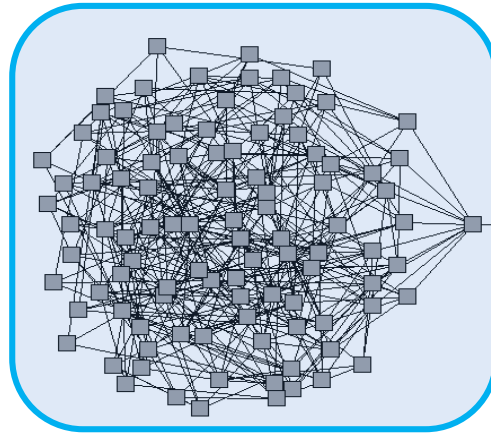
Barabási-Albert Random Graph

$$c_k = k^{-1}$$

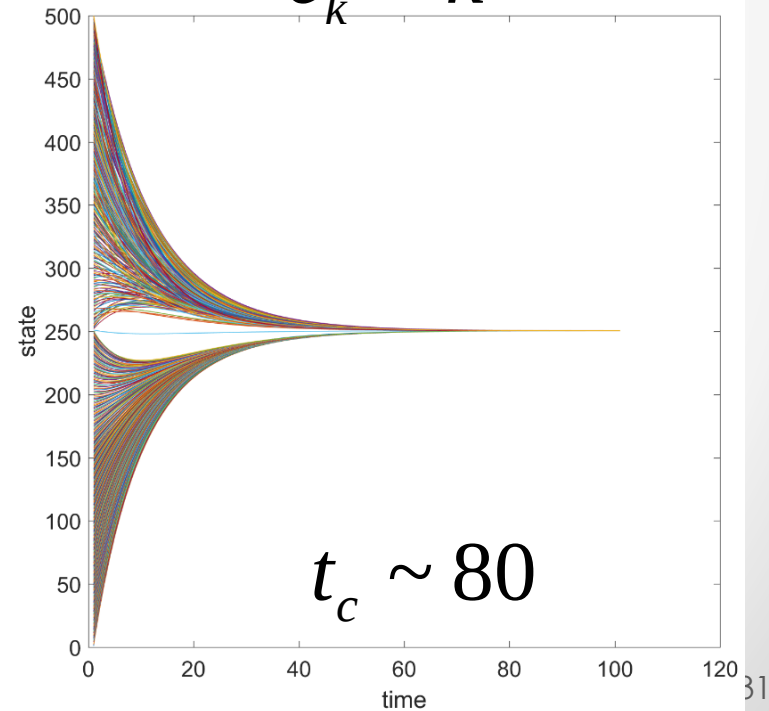
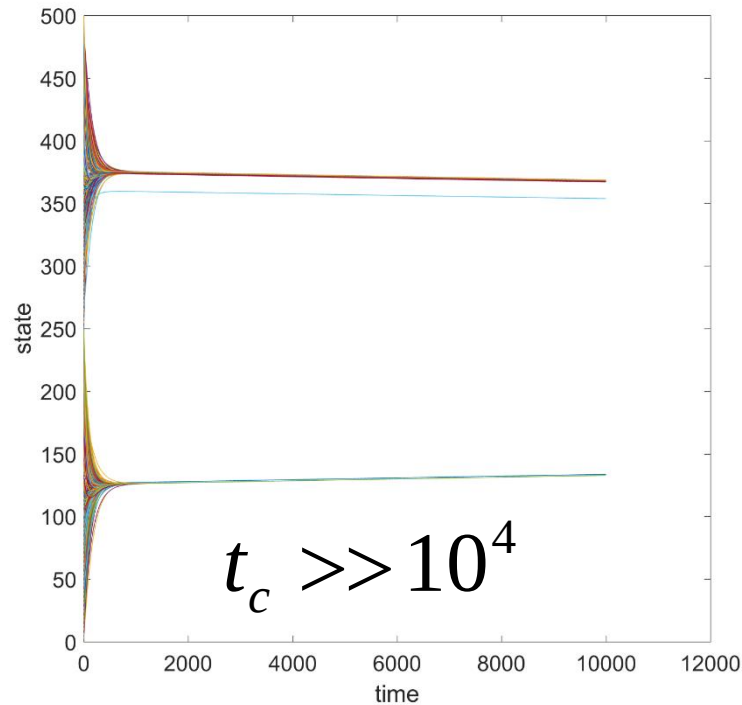


$$G(500, 6)$$

How much acceleration of consensus?



$$c_k = k^{-1}$$

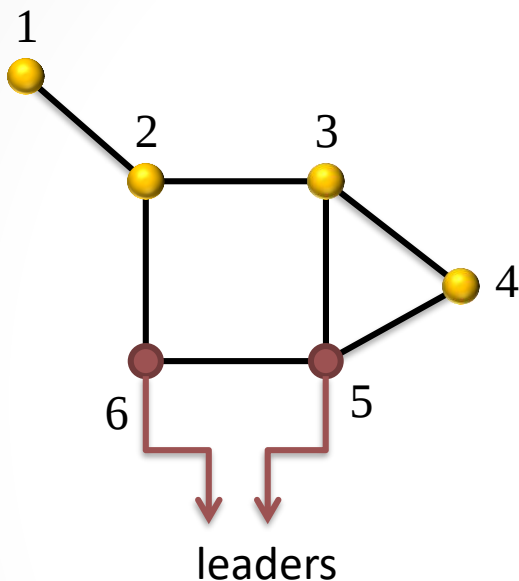


Leader-Followers Consensus



Let us consider the partition of the network into n_l leaders and $n-n_l$ followers.

Example:



$$\mathbf{L} = \begin{pmatrix} \boxed{\begin{matrix} 1 & -1 & 0 & 0 \\ -1 & 3 & -1 & 0 \\ 0 & -1 & 3 & -1 \\ 0 & 0 & -1 & 2 \end{matrix}} & \boxed{\begin{matrix} 0 & 0 \\ 0 & -1 \\ -1 & 0 \\ -1 & 0 \end{matrix}} \\ \begin{matrix} 0 & 0 & -1 & -1 \\ 0 & -1 & 0 & 0 \end{matrix} & \boxed{\begin{matrix} 3 & -1 \\ -1 & 2 \end{matrix}} \end{pmatrix}$$

followers

leaders

$$\mathbf{L}_l = \begin{pmatrix} 3 & -1 \\ -1 & 2 \end{pmatrix} \quad \mathbf{L}_f = \begin{pmatrix} 1 & -1 & 0 & 0 \\ -1 & 3 & -1 & 0 \\ 0 & -1 & 3 & -1 \\ 0 & 0 & -1 & 2 \end{pmatrix} \quad \mathbf{L}_{fl} = \begin{pmatrix} 0 & 0 \\ 0 & -1 \\ -1 & 0 \\ -1 & 0 \end{pmatrix}$$

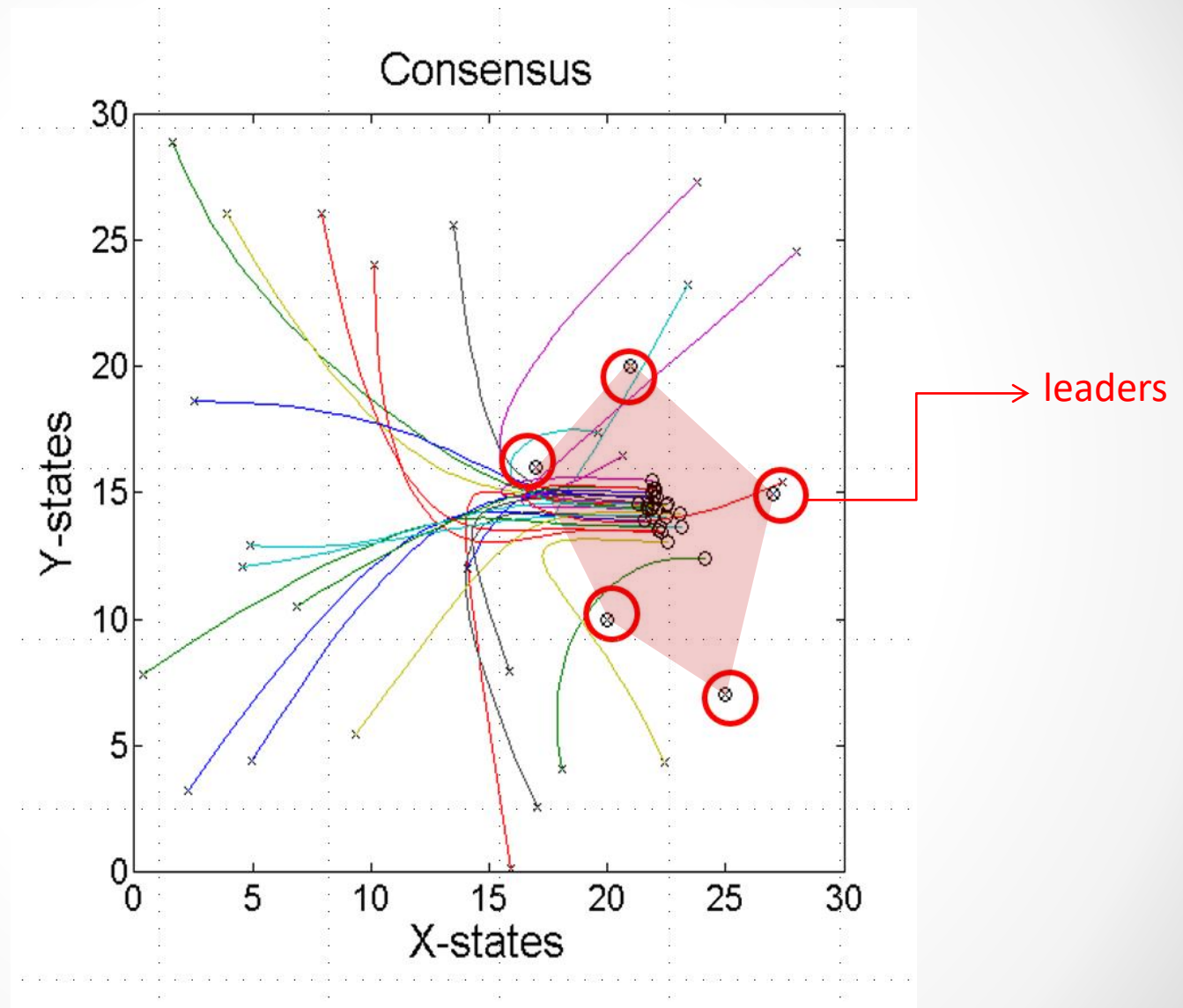
Leaders-followers consensus

The consensus dynamics of a leaders-followers system is described by:

$$\begin{bmatrix} \dot{\mathbf{u}}_f \\ \dot{\mathbf{u}}_l \end{bmatrix} = - \begin{bmatrix} \mathbf{L}_f & \mathbf{L}_{fl} \\ \mathbf{0} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{u}_f \\ \mathbf{u}_l \end{bmatrix} + \begin{bmatrix} \mathbf{0} \\ \mathbf{I} \end{bmatrix} \mathbf{u}$$

$$\dot{\mathbf{u}}_f = -\mathbf{L}_f \mathbf{u}_f - \mathbf{L}_{fl} \mathbf{u}_l$$

Leaders-followers consensus



Who is the best
Leader?



Leaders selection

Let us consider that the **best leader** is the one that leads to the fastest consensus of its followers.

Theorem: *The time of consensus averaged over all the nodes in the network is bounded as follows:*

$$\langle t_c \rangle \geq \frac{1}{n\mu_2} \sum_{p=1}^n \ln \left| \frac{\vec{\psi}_2(p) \left(\vec{\psi}_2 \cdot \vec{u}_0 \right)}{\delta} \right|.$$

*Is the **most central** agent
the best leader?*



Agents centrality

BC: betweenness centrality

CC: closeness centrality

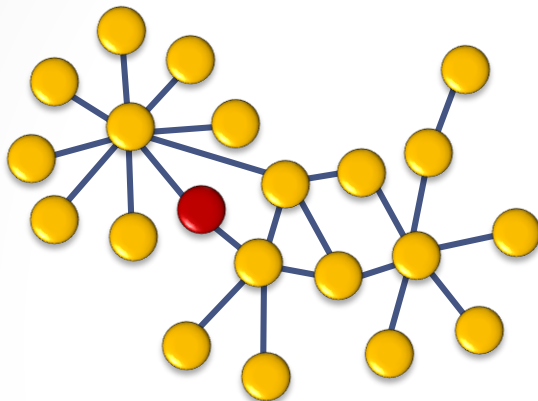
DC: degree centrality

EC: eigenvector centrality

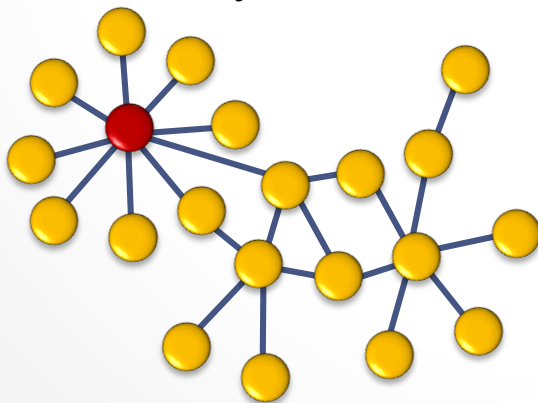
SC: subgraph centrality

Leaders selection

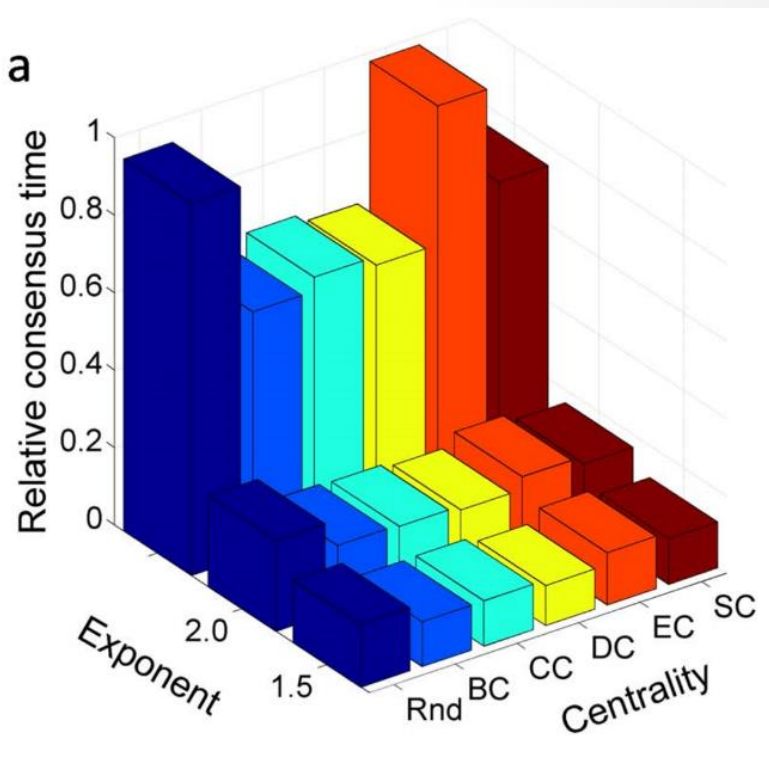
Random selection



Centrality-based

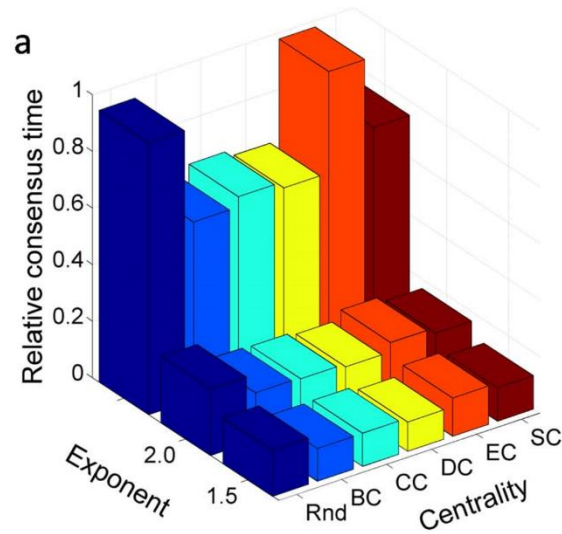


a

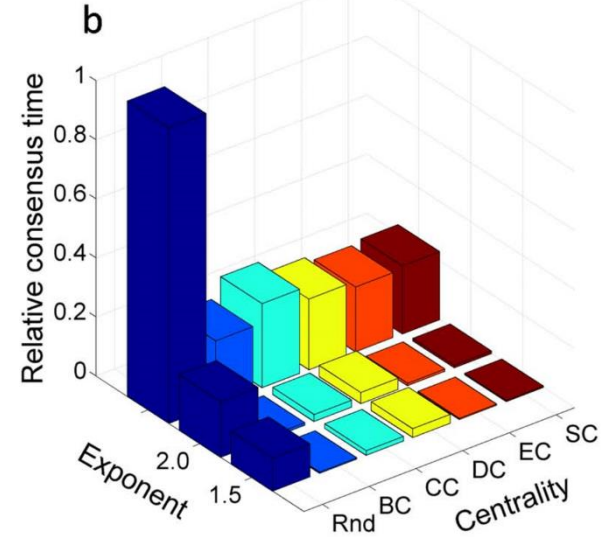


Leaders selection

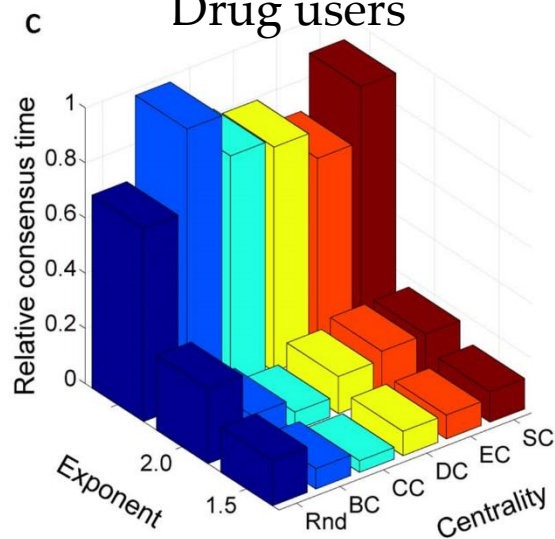
Sawmill



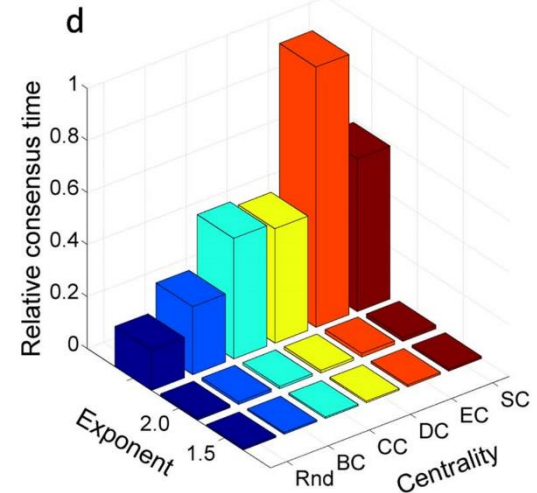
Corporate directors



Drug users

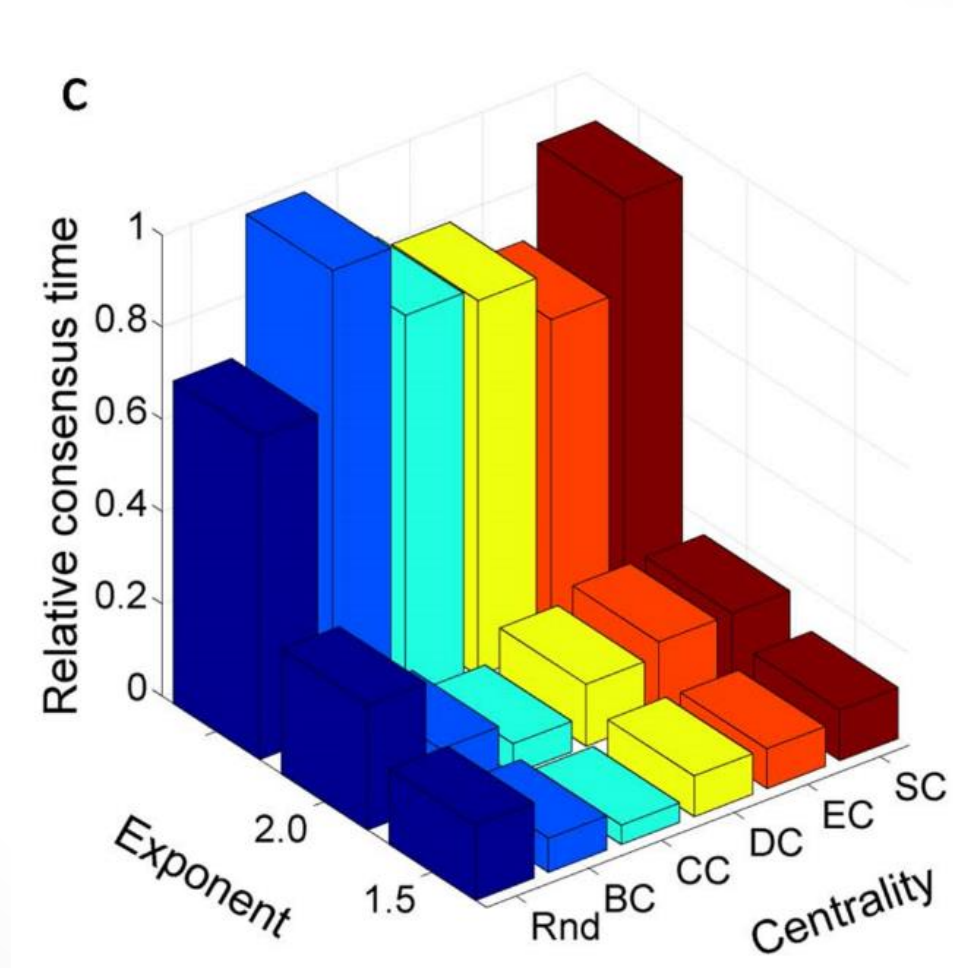


Random with communities

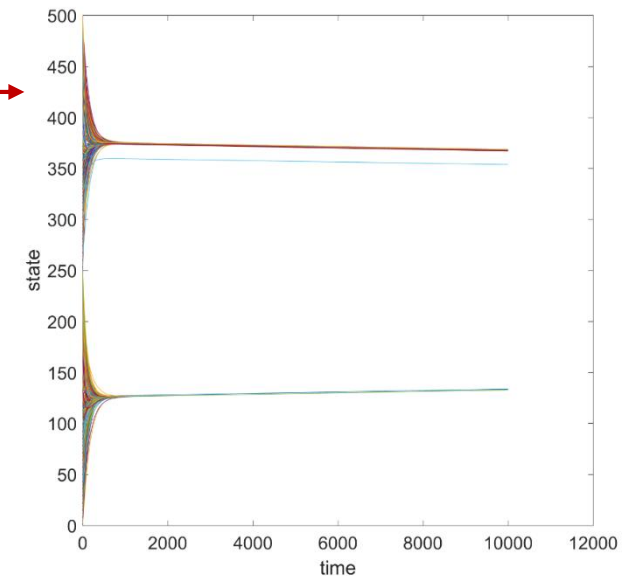
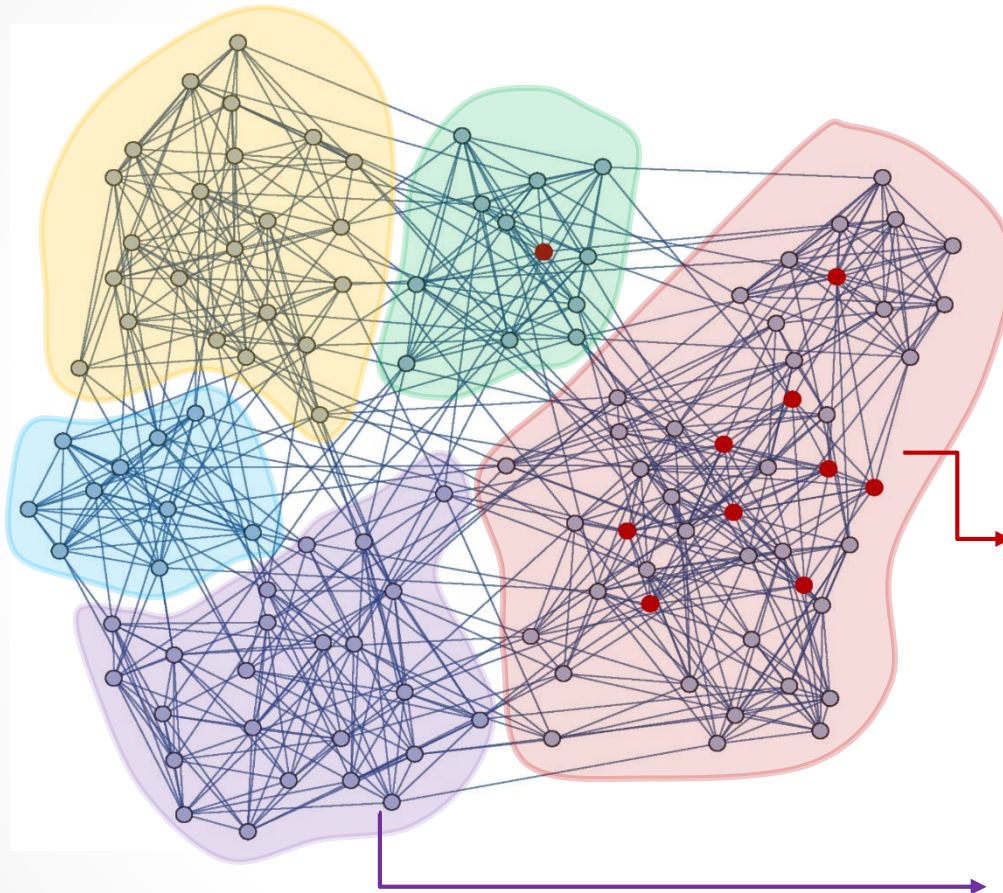


When random is better...

Injecting drug users



Or, the need of local leaders

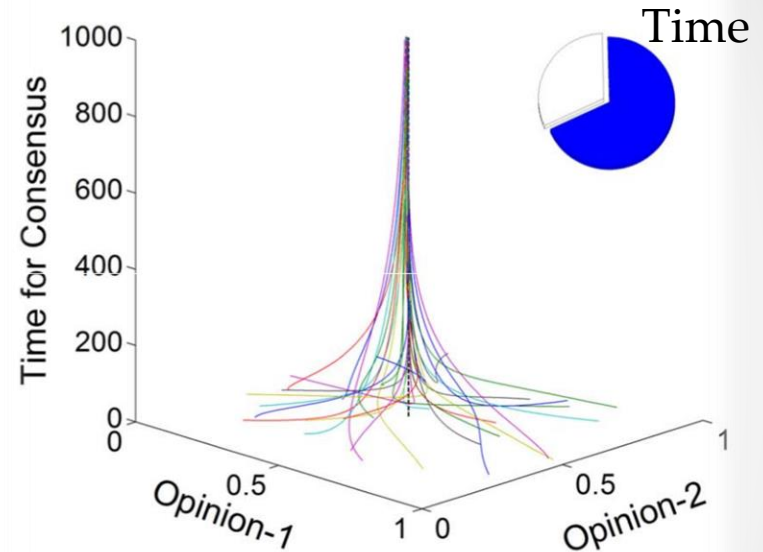
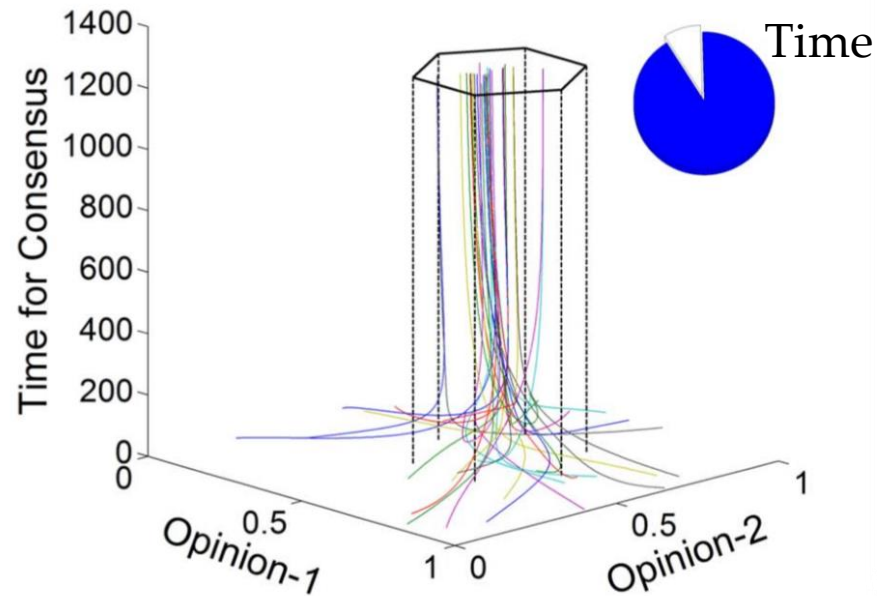


Leaders selection



LEADERS' COHESIVENESS

Leaders selection



LEADERS' COHESIVENESS

Sync under
long-range
influences

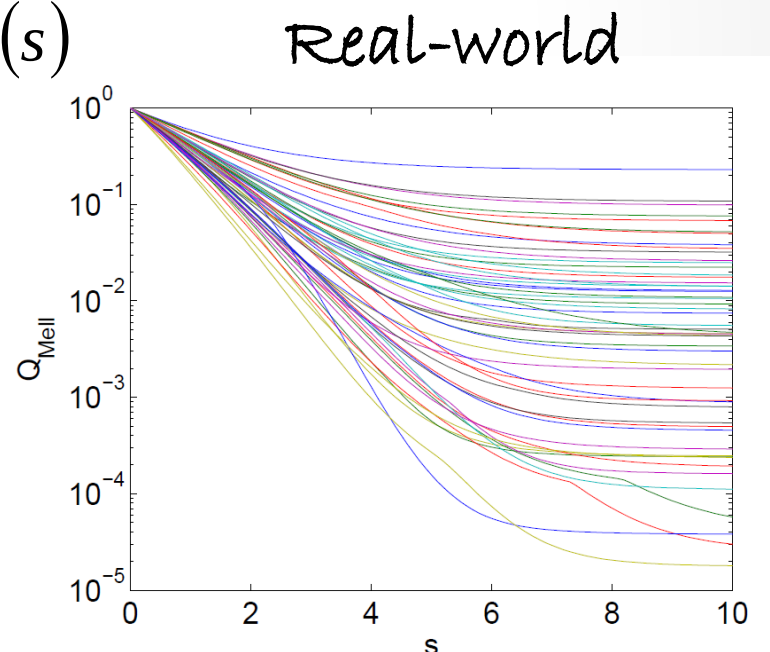
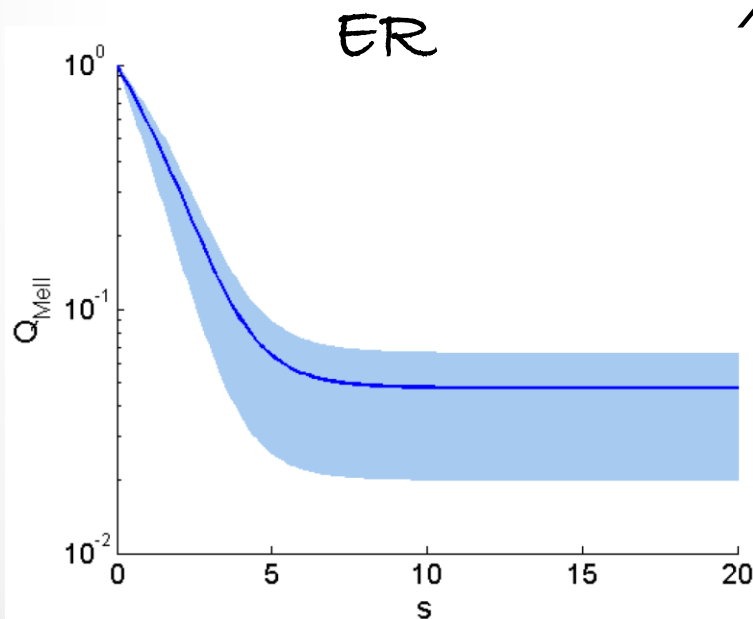


Generalised sync model

$$\dot{\vec{\theta}} = \vec{\omega} - \sigma \left(\sum_{d=1}^{d_{max}} d^{-s} \nabla_d \cdot \sin \left(\nabla_d^T \vec{\theta} \right) \right),$$

$$\dot{\vec{\theta}} = \vec{\omega} - \sigma \left(\nabla \cdot \sin \left(\nabla^T \vec{\theta} \right) \right) - \sigma \left(\sum_{d=2}^{d_{max}} e^{-\lambda d} \nabla_d \cdot \sin \left(\nabla_d^T \vec{\theta} \right) \right).$$

$$Q := \frac{\lambda_2(s)}{\lambda_n(s)}$$



Estrada, Gambuzza, Frasca, *SIAM J. Appl. Dyn. Syst.*, in press.

arXiv: 1704.01349 (2017).

Conclusions

- A generalisation of the *consensus dynamics model* is done to include *long-range influences* (LRI).
- LRI influences significantly the *rate of consensus* in networks.
- LRI may give rise to *superdiffusive behaviour* on networks under certain conditions.
- LRI influences significantly on *leaders selection* in networks.
- The LRI scheme has been extended to other dynamical processes on networks, such as (i) *synchronisation*; (ii) *epidemics* on spatial networks; (iii) *random walks* (iv) *replicator-mutator dynamics*; (v) *nonlinear diffusion*.



Thank you!
Merci!