

# Recent Advances in Partitioning Clustering Algorithms for Interval-Valued Data

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#### Outline



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#### Symbolic Data



- Symbolic Data Analysis (Bock and Diday (2000), Billard and Diday (2006), Diday and Noirhome (2008))
  - Aims to develop data analysis methods (clustering, factorial analysis, etc) to manage symbolic data
- Symbolic data generalizes usual categorical or quantitative data
  - A symbolic variable can take several values
- New types of variables
  - Set-valued, ordered list-valued, interval-valued, histogramvalued variables



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# **Interval-Value Data**



	Pulse Rate	Systolic pressure	Diastolic pressure
1	[60, 72]	[90,130]	[70,90]
2	[70,112]	[110,142]	[80,108]
3	[54,72]	[90,100]	[50,70]
4	[70,100]	[130,160]	[80,110]
5	[63,75]	[60,100]	[140,150]
6	[44,68]	[90,100]	[50,70]

Each object i is described by a vector of intervals

Interval-Valued Data Analysis Tools are required



#### Introduction









#### Introduction









# Some Data Analysis Methods for Interval-Valued Data

- Central Tendency, Dispersion, Histograms: De Carvalho (1995), Billard • and Diday (2003)
- Hierarchical and Pyramidal Clustering: Gowda and Diday (1991), Ichino • and Yaguchi (2004), Guru and Kinaragi (2005), Brito and De Carvalho (2008)
- Fatorial Analysis: Chouakria et al (2007), Lauro and Palumbo (2000), ۲ Palumbo and Verde (2000)
- Time Series Analysis: Maia, De Carvalho and Ludermir (2008), Arroyo ۲ and Maté (2009), Maia and De Carvalho (2010)
- Multidimensional scaling: Groenen et al (2006) ۲
- MLP: Munõz San Roque et al (2007) •
- Regression: Billard and Diday (2000), Lima Neto and De Carvalho • (2008), Lima Neto and De Carvalho (2010)



# **Dynamic Clustering Algorithm**



- Diday (1971), Diday and Simon (1976)
- Dynamic clustering are relocation algorithms
- They optimizes (locally) an adequacy criterion
- The adequacy criterion express the best fitting between a partition and the set of prototypes which represent the clusters
- Prototypes can be a set of individuals, a mean vector, a regression model, a factorial plan, etc
- k-means like algorithm: If the criterion is the variance and the prototypes are mean vectors of the clusters



# Dynamic Clustering Algorithm with Adaptive Distances

- Diday and Govaert (1974), Diday and Govaert (1977)
- There is a different distance for each cluster which changes at each iteration
- Main Steps
  - Initialization: Starts from a initial partition and alternates 3 steps
  - Step 1: Determination of the best prototypes
  - Step 2: Determination of the best distances
  - Step 3: Determination of the best partition
  - Repeat steps 1 to 3 until the convergence of the adequacy criterion



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## Partitioning Dinamic Clustering Algorithm for Interval-Valued Data

- Chavent and Lechevallier (2002), Souza and De Carvalho (2004), Chavent et al (2006), De Carvalho et al (2006-a, 2006b), Irpino and Verde (2008), De Carvalho and Lechevallier (2009-a, 2009-b)
- E: set of n examples described by p interval-valued variables
- Each example *i* is represented by a vector of intervals
  - $\mathbf{x}_i = (x_{i1}, \dots, x_{ip})$ , where  $x_{ij} = [a_{ij}, b_{ij}]$  (j=1,...,p)
- The prototype of cluster  $C_k$  is also represented as a vector of intervals

• 
$$y_k = (y_{k1}, ..., y_{kp})$$
, where  $y_{kj} = [\alpha_{kj}, \beta_{kj}]$  (k=1,...,K)



# **Partitioning Clustering Algorithms**



- These algorithms look for
  - a partition of *E* in *K* clusters  $(C_1, \ldots, C_K)$  and
  - their corresponding prototypes  $(\mathbf{y}_1, \dots, \mathbf{y}_K)$
- such that an adequacy criterion W is (locally) minimized
- Adequacy criterion:

$$W = \sum_{k=1}^{K} \sum_{i \in C_k} d(\mathbf{x}_i, \mathbf{y}_k)$$

- $\mathbf{x}_i = (x_{i1}, \dots, x_{ip})$ , where  $x_{ij} = [a_{ij}, b_{ij}]$  (i=1,...,n) (j=1,...,p)
- $y_k = (y_{k1}, \dots, y_{kp})$ , where  $y_{kj} = [\alpha_{kj}, \beta_{kj}]$  (k=1,...,K) (j=1,...,p)



# Non-Adaptive Dissimilarity Functions Between Vectors of Intervals

• Ichino and yaguchi (1994):  $a = (A_1, ..., A_p)$ ;  $b = (B_1, ..., B_p)$ 

$$d_q(a,b) = \left(\sum_{j=1}^p \left(\phi(A_j, B_j)\right)^q\right)^{\frac{1}{q}}, q \ge 1$$

$$\phi(\mathbf{A}_{j},\mathbf{B}_{j}) = |\mathbf{A}_{j} \oplus \mathbf{B}_{j}| - |\mathbf{A}_{j} \otimes \mathbf{B}_{j}| + \gamma (2|\mathbf{A}_{j} \otimes \mathbf{B}_{j}| - |\mathbf{A}_{j}| - |\mathbf{B}_{j}|)$$





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# Non-Adaptive Dissimilarity Functions Between Vectors of Intervals

- Non Adaptive Dissimilarity Functions
  - Euclidean, city-block, Hausdorff distances, Wasserstein distances
  - They are the same for all clusters
  - They do not change at each algorithm's iteration

$$d(\mathbf{x}_i, \mathbf{y}_k) = \sum_{j=1}^p d_j(x_{ij}, y_{kj})$$



# Dissimilarity Functions Between Intervals - I

• city-block distances

$$d(x_{ij}, y_{kj}) = |a_{ij} - \alpha_{kj}| + |b_{ij} - \beta_{kj}|$$

Hausdorff distances

$$d(x_{ij}, y_{kj}) = \max\{|a_{ij} - \alpha_{kj}|, |b_{ij} - \beta_{kj}|\}$$

• Euclidean distances

$$d(x_{ij}, y_{kj}) = (a_{ij} - \alpha_{kj})^2 + (b_{ij} - \beta_{kj})^2$$



# Dissimilarity Functions Between Intervals - II

• Wasserstein distance

$$d(x_{ij}, y_{kj}) = (m_{ij} - m_{kj})^2 + \frac{1}{3}(r_{ij} - r_{kj})^2$$

$$m_{ij} = \frac{(a_{ij} + b_{ij})}{2}$$
  $m_{kj} = \frac{(\alpha_{ij} + \beta_{ij})}{2}$ 

$$r_{ij} = \frac{(b_{ij} - a_{ij})}{2}$$
  $r_{kj} = \frac{(\beta_{ij} - \alpha_{ij})}{2}$ 



# Single Adaptive Dissimilarity Functions Between Vectors of Intervals - I

- Single Adaptive Dissimilarity Functions
  - Euclidean, city-block, Hausdorff distances, Wasserstein distances
  - They are parameterized by a weight vector

$$\boldsymbol{\lambda} = (\boldsymbol{\lambda}_1, \dots, \boldsymbol{\lambda}_p)$$

- The weight vector is the same for all clusters
- The weight vector changes at each algorithm's iteration

$$d_{\lambda}(\mathbf{x}_{i},\mathbf{y}_{k}) = \sum_{j=1}^{p} \lambda_{j} d_{j}(x_{ij},y_{kj})$$



# Single Adaptive Dissimilarity Functions Between Vectors of Intervals - II

- Single Adaptive Quadratic Distances
  - Mahalanobis distances
  - They are parameterized by a weight matrix **M**
  - The weight matrix is the same for all clusters
  - The weight matrix changes at each algorithm's iteration

$$d_{\mathbf{M}}(\mathbf{x}_{i},\mathbf{y}_{k}) = (\mathbf{x}_{iL} - \mathbf{y}_{kL})^{T} \mathbf{M}(\mathbf{x}_{iL} - \mathbf{y}_{kL}) + (\mathbf{x}_{iU} - \mathbf{y}_{kU})^{T} \mathbf{M}(\mathbf{x}_{iU} - \mathbf{y}_{kU})$$

$$\mathbf{x}_{iL} = (a_{i1}, \dots, a_{ip}) \qquad \mathbf{x}_{iU} = (b_{i1}, \dots, b_{ip})$$
$$\mathbf{y}_{kL} = (\boldsymbol{\alpha}_{k1}, \dots, \boldsymbol{\alpha}_{kp}) \qquad \mathbf{y}_{kL} = (\boldsymbol{\beta}_{k1}, \dots, \boldsymbol{\beta}_{kp})$$



# Cluster Adaptive Dissimilarity Functions Between Vectors of Intervals

- Cluster Adaptive Dissimilarity Functions
  - Euclidean, city-block, Hausdorff, Wasserstein distances
  - They are parameterized by weight vectors

$$\boldsymbol{\lambda}_{k} = (\boldsymbol{\lambda}_{k1}, \dots, \boldsymbol{\lambda}_{kp}) \ (k = 1, \dots, K)$$

- The weight vectors are different from one cluster to another
- The weight vectors change at each algorithm's iteration

$$d_{\boldsymbol{\lambda}_k}(\mathbf{x}_i, \mathbf{y}_k) = \sum_{j=1}^p \lambda_{kj} d_j(x_{ij}, y_{kj})$$





# Cluster Adaptive Dissimilarity Functions Between Vectors of Intervals - II

- Cluster Adaptive Quadratic Distances
  - Mahalanobis distances
  - They are parameterized by weight matrices  $\mathbf{M}_k$  (k=1,...,K)
  - The weight matrices are different from one cluster to another
  - The weight matrices change at each algorithm's iteration

$$d_{\mathbf{M}}(\mathbf{x}_{i},\mathbf{y}_{k}) = (\mathbf{x}_{iL} - \mathbf{y}_{kL})^{T} \mathbf{M}_{k} (\mathbf{x}_{iL} - \mathbf{y}_{kL}) + (\mathbf{x}_{iU} - \mathbf{y}_{kU})^{T} \mathbf{M}_{k} (\mathbf{x}_{iU} - \mathbf{y}_{kU})$$

$$\mathbf{x}_{iL} = (a_{i1}, \dots, a_{ip}) \qquad \mathbf{x}_{iU} = (b_{i1}, \dots, b_{ip})$$
$$\mathbf{y}_{kL} = (\boldsymbol{\alpha}_{k1}, \dots, \boldsymbol{\alpha}_{kp}) \qquad \mathbf{y}_{kL} = (\boldsymbol{\beta}_{k1}, \dots, \boldsymbol{\beta}_{kp})$$





- The partition of *E* in *K* clusters and the distances are fixed
- The best prototype  $y_k = (y_k^{\ 1}, \dots, y_k^{\ p})$  has the boundaries of the interval  $y_k^{\ j} = [\alpha_k^{\ j}, \beta_k^{\ j}]$  calculated according to
  - City-block distances:

$$\alpha_{kj}$$
 = Median { $a_{ij}$  :  $i \in C_k$ } and  $\beta_{kj}$  = Median { $b_{ij}$  :  $i \in C_k$ }

• Hausdorff distances (Chavent and Lechevallier 2002):  $\alpha_{kj} = \mu_{kj} - \rho_{kj}$  and  $\beta_{kj} = \mu_{kj} + \rho_{kj}$  where

$$\mu_{kj} = Median \{ m_{ij} : i \in C_k \} \text{ and } \\ \rho_{kj} = Median \{ r_{ij} : i \in C_k \}$$

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# Step 1: Definition of the best prototypes - II

• Euclidean and Mahalanobis distances:

 $\alpha_{kj}$ = Average { $a_{ij}$  :  $i \in C_k$ } and  $\beta_{kj}$  = Average { $b_{ij}$  :  $i \in C_k$ }

• Wasserstein distances (Irpino and Verde (2008):  $\alpha_{kj} = m_{kj} - r_{kj}$  and  $\beta_{kj} = m_{kj} + r_{kj}$  where

$$m_{kj} = Average \{m_{ij} : i \in C_k\}$$
 and  
 $r_{kj} = Average \{r_{ij} : i \in C_k\}$ 





- Euclidean, city-block, Haudorff, Wasserstein distances
- The partition and the prototypes are fixed
- The best vector of weights  $\lambda = (\lambda^1, \dots, \lambda^p)$ , which minimizes the adequacy criterion *W* under,

$$\lambda_j > 0$$
 and  $\prod_{j=1}^p \lambda_j = 1$ 

has its components computed according to

$$\lambda_{j} = \frac{\left\{\prod_{h=1}^{p} \left(\sum_{k=1}^{K} \left[\sum_{i \in C_{k}} d_{h}(x_{ih}, y_{ih})\right]\right)\right\}^{\frac{1}{p}}}{\sum_{k=1}^{K} \left[\sum_{i \in C_{k}} d_{j}(x_{ij}, y_{ij})\right]}$$



# Step 2: Definition of the Single best distances - II

- Mahalanobis distances
- The best matrix of weights **M**, which minimizes the adequacy criterion J under,

 $det(\mathbf{M}) = 1$ 

is computed according to

$$\mathbf{M} = \left[\det(\mathbf{Q})\right]^{\frac{1}{p}} \mathbf{Q}^{-1} \qquad \mathbf{Q} = \sum_{k=1}^{K} \mathbf{Q}_{k}$$
$$\mathbf{Q}_{k} = \sum_{i \in C_{k}} \left[ (\mathbf{x}_{iL} - \mathbf{y}_{kL}) (\mathbf{x}_{iL} - \mathbf{y}_{kL})^{T} + (\mathbf{x}_{iU} - \mathbf{y}_{kU}) (\mathbf{x}_{iU} - \mathbf{y}_{kU})^{T} \right]$$



# Step 2: Definition of the Cluster best distances - I

- Euclidean, city-block Haudorff, Wasserstein distances
- The partition and the prototypes are fixed
- The best vector of weights  $\lambda_k = (\lambda_{k1}, \dots, \lambda_{kp})$ , which minimizes the adequacy criterion *J* under,

$$\lambda_{kj} > 0$$
 and  $\prod_{j=1}^{p} \lambda_{kj} = 1$ 

has its components calculated according to

$$\lambda_{kj} = \frac{\left\{\prod_{h=1}^{p} \left(\sum_{i \in C_{k}} d_{h}(x_{ih}, y_{ih})\right)\right\}^{\frac{1}{p}}}{\left[\sum_{i \in C_{k}} d_{j}(x_{ij}, y_{ij})\right]}$$



# Step 2: Definition of the Cluster best distances - II

- Mahalanobis distances
- The best matrices of weights *M<sub>k</sub>* (k=1,...,K), which minimizes the adequacy criterion *J* under,

 $\det(\mathbf{M}_k) = 1$ 

is computed according to

$$\mathbf{M}_{k} = \left[\det(\mathbf{Q}_{k})\right]^{\frac{1}{p}} \mathbf{Q}_{k}^{-1}$$

$$\mathbf{Q}_{k} = \sum_{i \in C_{k}} \left[ (\mathbf{x}_{iL} - \mathbf{y}_{kL}) (\mathbf{x}_{iL} - \mathbf{y}_{kL})^{T} + (\mathbf{x}_{iU} - \mathbf{y}_{kU}) (\mathbf{x}_{iU} - \mathbf{y}_{kU})^{T} \right]$$



## Step 3: Definition of the best partition



- The prototypes and the distances are fixed
- The best partition (C<sub>1</sub>,...,C<sub>K</sub>), which minimizes the adequacy criterion J, has its clusters updated according to

$$C_{k} = \{i \in E : d(\mathbf{x}_{i}, \mathbf{y}_{k}) \leq d(\mathbf{x}_{i}, \mathbf{y}_{h}), \forall h \neq k\}$$





## **Cluster and partition interpretation**



- Important step in clustering analysis
- For usual quantitative data, Celeux et al (1989) introduced a family of indices for cluster and partition interpretation
- For this case, the dispersions decompose into the dispersions within clusters plus the dispersions between clusters.
- Chavent et al (2006) presented an approach to measure the partition (or cluster) quality which holds even if the dispersions does not decomposes as before



## **Cluster and partition interpretation**



- Let us consider
  - A partition  $C = (C_1, ..., C_K)$  of E in K clusters of cardinality  $n_k$
  - Each cluster has a prototype  $\mathbf{y}_k = (y_k^1, \dots, y_k^p)$
  - Let us consider a overall prototype of *E* as  $\mathbf{y} = (y^1, \dots, y^p)$
- Overall Dispersion

$$T = \sum_{i=1}^{n} d(\mathbf{x}_i, \mathbf{y}) = \sum_{k=1}^{K} \sum_{i \in C_k} d(\mathbf{x}_i, \mathbf{y})$$



# **Overall Prototype - I**



- The overall prototype  $\mathbf{y} = (y_1, \dots, y_p)$  has the boundaries of the interval  $y_j = [\alpha_j, \beta_j]$  calculated according to
  - City-block distances:

 $\alpha_j$  = Median { $a_{ij}$  for all  $i \in E$ } and  $\beta_j$  = Median { $b_{ij}$  for all  $i \in E$ }

• Hausdorff distances:  $\alpha_j = \mu_j - \rho_j$  and  $\beta_j = \mu_j + \rho_j$  where

 $\mu_i$  = median { $m_{ij}$  for all  $i \in E$ } and

 $\rho_j$  = median { $r_{ij}$  for all  $i \in E$ }



# **Overall Prototype - II**



- The overall prototype  $\mathbf{y} = (y_1, \dots, y_p)$  has the boundaries of the interval  $y_i = [\alpha_i, \beta_i]$  calculated according to
  - Euclidean and Mahalanobis distances:

 $\alpha_j = Average \{a_{ij} \text{ for all } i \in E\} \text{ and } \beta_j = Average \{b_{ij} \text{ for all } i \in E\}$ 

• Wasserstein distances:  $\alpha_{kj} = m_{kj} - r_{kj}$  and  $\beta_{kj} = m_{kj} + r_{kj}$  where  $m_{ki} = Average \{m_{ii}: i \in C_k \text{ for all } i \in E\}$  and

$$r_{kj} = Average \{r_{ij} : i \in C_k \text{ for all } i \in E\}$$



# **Overall dispersion - I**



$$T = \sum_{i=1}^{n} d(\mathbf{x}_i, \mathbf{y}) = \sum_{k=1}^{K} \sum_{i \in C_k} d(\mathbf{x}_i, \mathbf{y})$$

- It decomposes
  - into the sum of the cluster-specific overall dispersion

$$T = \sum_{k=1}^{K} T_k \qquad T_k = \sum_{i \in C_k} d(\mathbf{x}_i, \mathbf{y})$$



# **Overall dispersion - II**



 into the sum of the variable-specific overall dispersion (except for the Mahalanobis distance)

$$T = \sum_{j=1}^{p} T_{j}$$

$$T_{j} = \sum_{k=1}^{K} \sum_{i \in C_{k}} d_{j}(x_{ij}, y_{j})$$

$$T_j = \sum_{k=1}^K \sum_{i \in C_k} \lambda_j d_j(x_{ij}, y_j)$$

$$T_j = \sum_{k=1}^K \sum_{i \in C_k} \lambda_{kj} d_j(x_{ij}, y_j)$$

• into the sum of the variable-cluster-specific overall dispersion (except for the Mahalanobis distance)

$T = \sum_{k=1}^{K} \sum_{j=1}^{p} T_{kj}$	$T_{kj} = \sum_{i \in C_k} d_j(x_{ij}, y_j)$
$T_{kj} = \sum_{i \in C_k} \lambda_j d_j(x_{ij}, y_j)$	$T_{kj} = \sum_{i \in C_k} \lambda_{kj} d_j(x_{ij}, y_j)$





$$W = \sum_{k=1}^{K} \sum_{i \in C_k} d(\mathbf{x}_i, \mathbf{y}_k)$$

- It decomposes
  - into the sum of the cluster-specific within-cluster dispersion

$$W = \sum_{k=1}^{K} W_k \qquad \qquad W_k = \sum_{i \in C_k} d(\mathbf{x}_i, \mathbf{y}_k)$$



# Within-cluster dispersion - II



 into the sum of the variable-specific within-cluster dispersion (except for the Mahalanobis distance)

$$W = \sum_{j=1}^{p} W_{j} \qquad \qquad W_{j} = \sum_{k=1}^{K} \sum_{i \in C_{k}} d_{j}(x_{ij}, y_{kj})$$
$$W_{j} = \sum_{k=1}^{K} \sum_{i \in C_{k}} \lambda_{j} d_{j}(x_{ij}, y_{kj}) \qquad \qquad W_{j} = \sum_{k=1}^{K} \sum_{i \in C_{k}} \lambda_{kj} d_{j}(x_{ij}, y_{kj})$$

 into the sum of the variable-cluster-specific within-cluster dispersion (except for the Mahalanobis distance)

$$W = \sum_{k=1}^{K} \sum_{j=1}^{p} W_{kj} \qquad W_{kj} = \sum_{i \in C_k} d_j(x_{ij}, y_{kj})$$
$$W_{kj} = \sum_{i \in C_k} \lambda_j d_j(x_{ij}, y_{kj}) \qquad W_{kj} = \sum_{i \in C_k} \lambda_{kj} d_j(x_{ij}, y_{kj})$$



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$$B = \sum_{k=1}^{K} n_k d(\mathbf{y}_k, \mathbf{y})$$

- It decomposes
  - into the sum of the cluster-specific between-cluster dispersion

$$B = \sum_{k=1}^{K} B_k \qquad B_k = n_k d(\mathbf{y}_k, \mathbf{y})$$





 into the sum of the variable-specific between-cluster dispersion (except for the Mahalanobis distance)

$$B = \sum_{j=1}^{p} B_{j} \qquad B_{j} = \sum_{k=1}^{n} n_{k} d_{j}(y_{kj}, y_{k})$$

$$B_{j} = \sum_{k=1}^{K} n_{k} \lambda_{j} d_{j}(y_{kj}, y_{k}) \qquad B_{j} = \sum_{k=1}^{K} n_{k} \lambda_{kj} d_{j}(y_{kj}, y_{k})$$

 into the sum of the variable-cluster-specific between-cluster dispersion (except for the Mahalanobis distance)

$$B = \sum_{k=1}^{K} \sum_{j=1}^{p} B_{kj} \qquad B_{kj} = n_k d_j (y_{kj}, y_j)$$
$$B_{kj} = n_k \lambda_j d_j (y_{kj}, y_j) \qquad B_{kj} = n_k \lambda_{kj} d_j (y_{kj}, y_j)$$



# Relations Between Overall, Within and Between Dispersion - I

- T = B + W (Euclidean, Mahalanobis and Wasserstein distances)
- T<sub>k</sub> = B<sub>k</sub> + W<sub>k</sub> for k=1,...,K (Euclidean, Mahalanobis and Wasserstein distances)
- T<sub>j</sub> = B<sub>j</sub> + W<sub>j</sub> for j=1,...,p (Euclidean and Wasserstein distances)
- T<sub>kj</sub> = B<sub>kj</sub> + W<sub>kj</sub> for k=1,...,K and j=1,...,p (Euclidean and Wasserstein distances)



# Relations Between Overall, Within and Between Dispersion - II

- For all distances, the following relations hold:
  - T > W
  - *T<sub>k</sub>* > *W<sub>k</sub>* for k=1,...,K
  - $T_j > W_j$  for j=1,...,p
  - $T_{kj} > W_{kj}$  for k=1,...,K and j=1,...,p



# **Some Partition Interpretation Indices**



• **Overall heterogeneity index**: it measures the quality of a partition  $C = (C_1, ..., C_K)$  of  $\Omega$  in K clusters

$$Q(C) = \frac{T - W}{T} = 1 - \frac{W}{T}$$

 $0 \leq Q(C) \leq 1$ 

• Rule: a partition C in K clusters is better than a partition C' in K clusters if Q(C) > Q(C')





• Overall heterogeneity index with respect to single variables: it measures the quality of a partition  $C = (C_1, ..., C_K)$  of  $\Omega$  in K clusters concerning the *j*-th variables

$$Q_{j}(C) = \frac{T_{j} - W_{j}}{T} = 1 - \frac{W_{j}}{T}$$

- This index measures the discriminant power of the *j*-th variable in the partition  $C = (C_1, ..., C_K)$
- The comparison between Q<sub>j</sub> and Q evaluates if the discriminant power of the *j*-th variable is above or below the average



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# **Some Cluster Interpretation Indices**



- Cluster heterogeneity indices
  - The proportion of the overall dispersion in cluster  $C_k$

$$T(k) = \frac{T_k}{T} \qquad \sum_{k=1}^{K} T(k) = 1$$

• The relative contribution of cluster  $C_k$  to the overall within-cluster dispersion

$$W(k) = \frac{W_k}{W} \qquad \sum_{k=1}^{K} W(k) = 1$$

• A large value of W(k) indicates that cluster  $C_k$  is relatively heterogeneous in comparison with the other clusters



# **Some Cluster Interpretation Indices**



- Cluster heterogeneity indices
  - The quality of a cluster  $C_k$

$$Q(C_k) = \frac{T_k - W_k}{T_k} = 1 - \frac{W_k}{T_k}$$

This indice measures the gain of homogeneity of the cluster C<sub>k</sub> obtained when replacing the overall prototype y by the prototype y<sub>k</sub> in the calculation of the homogeneity



#### **Some Cluster Interpretation Indices**



- Cluster heterogeneity indices with respect to sigle variables
  - The quality of a cluster  $C_k$  concerning the *j*-th variable

$$Q_{j}(C_{k}) = \frac{T_{kj} - W_{kj}}{T_{kj}} = 1 - \frac{W_{kj}}{T_{kj}}$$

• Rule: the *j*-th variable characterizes the cluster  $C_k$  if  $Q_j(C_k) > Q(C_k)$ 



#### City Temperature Interval-Valued Data Set

Available at http://www.bbc.co.uk/weather/world/city\_guides/.

- gives the average minimal and average maximal monthly temperatures of cities in degrees centigrade
- the data set consists of 503 cities described by 12 intervalvalued variables.
- In this example, the algorithm uses single adaptive city-block distances
- For a fixed number K = {1,...,10}, the algorithm is run 100 times and the best result is selected



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#### City Temperature Interval-Valued Data Set

	January	February	 November	December
Amsterdam	[-4, 4]	[-5, 3]	 [1, 10]	[-1, 4]
Athens	[6, 12]	[6, 12]	 [11, 18]	[8, 14]
Mauritius	[22, 28]	[22, 29]	 [19, 27]	[21, 28]
Vienna	[-2, 1]	[-1, 3]	 [2, 7]	[1, 3]
Zurich	[-11, 9]	[-8, 15]	 [0, 19]	[-11, 8]



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# Determination of the number of clusters

SPAD Software, Gomes Da Silva (2009): peaks on the graph of the ``second order differences'' of the clustering criterion:  $W^{(K-1)} + W^{(K+1)} - 2 W^{(K)}$  (K=2,...,9)







**Cluster 1:** the cities have very cold temperatures in winter similar to that of northern and eastern Europe **Cluster 2:** the cities have temperatures similar to that of southern Europe

- **Cluster 3:** the cities have temperatures similar to that of western and central Europe.
- **Cluster 4:** the cities have temperatures similar to that of cities located in the southern hemisphere.
- **Cluster 5:** the cities have a tropical climate and warm to hot temperatures





# **Partition quality**

Q(C) = 62.82

#### **Partition quality / Variable j**

Variable	Qj(C)	
January	69.49	
February	70.68	
March	71.20	
April	66.54	
May	56.32	
June	46.81	
July	41.09	
August	42.65	
September	52.66	
October	64.16	
November	69.75	
December	69.78	
	Discriminant	
	months	



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#### **Most discriminant months**





#### **Least discriminant months**





Cluster	quality	$Q(C_1)=71.65$	$Q(C_2)=16.14$	$Q(C_3) = 68.67$
	Variable	$Q_j(C_1)$	$Q_j(C_2)$	$Q_j(C_3)$
	January	76.15	23.10	76.59
	February	78.28	20.51	77.49
	March	79.22	24.80	79.22
Cluster quality/	April	70.83	1.46	73.40
	May	62.94	6.17	52.02
Variable j	June	56.27	15.53	34.50
	July	53.51	22.33	25.32
	August	57.73	22.39	30.93
	September	66.86	16.84	52.84
	October	71.52	1.47	72.27
	November	74.74	10.52	80.76
	December	74.72	21.42	78.86



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Variable



#### $Q(C_4)=46.01$ $Q(C_5)=70.78$

O(CE)

O(C)

Cluster quality/ Variable j

valiable	$\mathbf{Q}_{j}(\mathbf{Q}_{4})$	$Q_{j}(UJ)$
January	63.04	72.77
February	62.12	73.93
March	44.01	75.79
April	10.09	78.64
May	19.15	73.18
June	50.84	57.84
July	62.45	36.85
August	60.29	39.19
September	37.40	63.14
October	1.07	77.99
November	22.18	78.50
December	55.00	73.85



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![](_page_53_Picture_2.jpeg)

### **Some Remarks**

![](_page_54_Picture_1.jpeg)

- Interval modelling
- Others distance functions
- Set-valued, list-valued, Histogram-valued data
- Mixed-feature type symbolic data

![](_page_54_Picture_6.jpeg)

Unsupervised pattern recognition models for mixed feature-type symbolic data Francisco de A.T. de Carvalho<sup>\*</sup>, Renata M.C.R. de Souza

![](_page_54_Picture_8.jpeg)

#### Some Remarks

![](_page_55_Picture_1.jpeg)

- Others classification structures: overlapping clusters
- Clustering mixtures

![](_page_55_Picture_4.jpeg)

![](_page_56_Picture_1.jpeg)

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![](_page_56_Picture_9.jpeg)

![](_page_57_Picture_1.jpeg)

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![](_page_57_Picture_5.jpeg)

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![](_page_57_Picture_9.jpeg)

SODAS and ASSO projects: http://www.info.fundp.ac.be/asso/objective.htm

![](_page_57_Picture_11.jpeg)

![](_page_58_Picture_1.jpeg)

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![](_page_58_Picture_6.jpeg)

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![](_page_59_Picture_1.jpeg)

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![](_page_59_Picture_7.jpeg)

![](_page_60_Picture_1.jpeg)

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![](_page_60_Picture_7.jpeg)

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![](_page_61_Picture_1.jpeg)

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![](_page_61_Picture_8.jpeg)

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![](_page_62_Picture_8.jpeg)

![](_page_63_Picture_0.jpeg)

#### Thank you

![](_page_63_Picture_2.jpeg)

![](_page_63_Picture_3.jpeg)